



# CANopen

## Reference Manual

# stepIM

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# **1 Introduction**

## **1.1 About This Manual**

This manual describes the implementation of CiA 402 and CiA 301 CANopen protocols in the stepIM digital servo drive. This manual is not meant to replace the CANopen specifications, or to reproduce them.

This manual is intended for skilled personnel who have been trained to work with the equipment described.

## **1.2 Documentation Format – Object Dictionary**

The CAN objects are presented and described in the following format:

## 0xnnnn – Example Name

### Object Description

<b>Index</b>	nnnn
<b>Description</b>	Description of the object
<b>Object Code</b>	Variable   Array   Record
<b>Data Type</b>	Integer8   Integer16   Integer32 Unsigned8   Unsigned16   Unsigned32 Real32   Visible_String PDO_COMM_PAR   PDO_MAPPING IDENTITY

### Entry Description for Variable and Record Objects

<b>Access</b>	Read/Write   Read Only   Constant
<b>PDO Mapping</b>	Yes   No
<b>Default Value</b>	The object's default value.
<b>Value Range</b>	Discrete values and ranges of values.
<b>Unit</b>	When the object value implies units of measure, these units are specified.
<b>Lower Limit</b>	Lowest value in the object's ranges of values.
<b>Upper Limit</b>	Highest value in the object's ranges of values.

### Entry Description for Array Objects

<b>Sub-Index</b>	nnn
<b>Description</b>	Description of the sub-index
<b>Data Type</b>	Integer8   Integer16   Integer32 Unsigned8   Unsigned16 Unsigned32   Real32   Visible_String
<b>Access</b>	Read/Write   Read Only   Constant
<b>PDO Mapping</b>	Yes   No
<b>Default Value</b>	The object's default value.
<b>Unit</b>	When the object value implies units of measure, these units are specified.
<b>Lower Limit</b>	Lowest value in the object's ranges of values.
<b>Upper Limit</b>	Highest value in the object's ranges of values.
<b>Value Range</b>	Discrete values and ranges of values.

## 2 Communication Segment

### 1000h – Device Type

#### Object Description

<b>Index</b>	1000
<b>Description</b>	This object describes the type of the logical device and its functionality. It is comprised of a 16 bit field that describes the device profile, and a second 16 bit field that gives additional information about the specific functionality of the device.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

#### Entry Description

<b>Access</b>	Constant
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00020192
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

### 1001h – Error Register

#### Object Description

<b>Index</b>	1001
<b>Description</b>	<p>This object is an error register for the device. It is a field of 8 bits, each of which indicates a particular type of error. If a bit is set to 1, the specified error has occurred.</p> <p>The bits have the following meaning:</p> <ul style="list-style-type: none"> <li>0: generic error</li> <li>1: current</li> <li>2: voltage</li> <li>3: temperature</li> <li>4: communication error (overrun, error state)</li> <li>5: device profile specific</li> <li>6: reserved</li> <li>7: manufacturer specific</li> </ul>
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned8

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFF

**1003h – Predefined Error Field****Object Description**

<b>Index</b>	1003
<b>Description</b>	This object holds errors that have occurred on the device and have been signaled via the Emergency object. It is an error history. Writing to sub-index 0 deletes the entire error history
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned32

**Entry Description**

<b>Sub-Index</b>	000
<b>Description</b>	Number of Errors
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFE

  

<b>Sub-Index</b>	001
<b>Description</b>	Standard Error Field
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Standard Error Field
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	003
<b>Description</b>	Standard Error Field
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	004
<b>Description</b>	Standard Error Field
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	005
<b>Description</b>	Standard Error Field
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	006
<b>Description</b>	Standard Error Field
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	007
<b>Description</b>	Standard Error Field
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	008
<b>Description</b>	Standard Error Field
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	009
<b>Description</b>	Standard Error Field
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF



<b>Sub-Index</b>	010
<b>Description</b>	Standard Error Field
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 1005h – COB-ID SYNC

### Object Description

<b>Index</b>	1005
<b>Description</b>	This object defines the COB ID of the synchronization object (SYNC). The device generates a SYNC message if bit 30 is set. The meaning of other bits is the same as for other communication objects.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x80000080
<b>Lower Limit</b>	0x00000001
<b>Upper Limit</b>	0xFFFFFFFF

## 1006h – Communication Cycle Period

### Object Description

<b>Index</b>	1006
<b>Description</b>	This object defines the communication cycle period, in microseconds. Its value is 0 if it is not used.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No

<b>Default Value</b>	0x00000FA0
<b>Unit</b>	microseconds
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

## 1007h – Synchronous Window Length

### Object Description

<b>Index</b>	1007
<b>Description</b>	This object contains the length of the time window for synchronous messages, in microseconds. Its value is 0 if it is not used.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x000003E8
<b>Unit</b>	microseconds
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

## 1008h – Manufacturer Device Name

### Object Description

<b>Index</b>	1008
<b>Description</b>	This object contains the name of the device as given by the manufacturer.
<b>Object Code</b>	Variable
<b>Data Type</b>	Visible_String

### Entry Description

<b>Access</b>	Constant
<b>PDO Mapping</b>	No
<b>Default Value</b>	stepIM
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

## 1009h – Manufacturer Hardware Version

**Object Description**

<b>Index</b>	1009
<b>Description</b>	This object contains the manufacturer hardware version description.
<b>Object Code</b>	Variable
<b>Data Type</b>	Visible_String

**Entry Description**

<b>Access</b>	Constant
<b>PDO Mapping</b>	No
<b>Default Value</b>	00
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

**100Ah – Manufacturer Software Version****Object Description**

<b>Index</b>	100A
<b>Description</b>	This object contains the manufacturer software version description.
<b>Object Code</b>	Variable
<b>Data Type</b>	Visible_String

**Entry Description**

<b>Access</b>	Constant
<b>PDO Mapping</b>	No
<b>Default Value</b>	-
<b>Lower Limit</b>	0
<b>Upper Limit</b>	0

**1010h – Store Parameter Field****Object Description**

<b>Index</b>	1010
--------------	------

<b>Description</b>	<p>This object controls the saving of parameters in non-volatile memory.</p> <p>With read access, the device provides information about its save capabilities. Sub-indexes reference different groups of parameters.</p> <p>Sub-index 1: all parameters</p> <p>Parameters are saved when 0x65766173 (ASCII value of "SAVE") is written to the appropriate sub-index.</p>
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned32

**Entry Description**

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x1
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7F

<b>Sub-Index</b>	001
<b>Description</b>	Save all Parameters
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 1011h – Restore Default Parameters

### Object Description

<b>Index</b>	1011
<b>Description</b>	<p>This object controls the restoring of default parameters. With read access, the device provides information about its restore capabilities. Sub-indexes reference different groups of parameters.</p> <p>Sub-index 1: all parameters</p> <p>Parameters are restored when 0x64616F6C (ASCII value of "LOAD") is written to the appropriate sub-index.</p>
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x1
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7F

<b>Sub-Index</b>	001
<b>Description</b>	Restore all Default Parameters
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 1013h – High Resolution Time Stamp

### Object Description

<b>Index</b>	1013
<b>Description</b>	This object contains the drives internal time at a resolution of microseconds. It can be mapped into a PDO in order to define a high resolution time stamp. It can be used to synchronize clocks of multiple drives over CANopen network as follows: map object 1013h to RPDO, a high-resolution time stamp producer transmits a time stamp over the CANopen network, and each drive adjusts its internal clock according to the value that the producer sent.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	<b>SDO:</b> Read/Write <b>PDO:</b> Read
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x00000000
<b>Unit</b>	microsecond
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

## 1014h – COB-ID EMCY

### Object Description

<b>Index</b>	1014
<b>Description</b>	This object defines the COB-ID used for the emergency message (EMCY).
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x80
<b>Lower Limit</b>	0x1
<b>Upper Limit</b>	0xFFFFFFFF

**1015h – Inhibit Time Emergency****Object Description**

<b>Index</b>	1015
<b>Description</b>	This object defines the inhibit time used for the emergency message. The time must be a multiple of 100 milliseconds.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	100 millisecond (ms)
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFF

**1016h – Heartbeat Consumer Entries****Object Description**

<b>Index</b>	1016
<b>Description</b>	The consumer heartbeat time defines the expected heartbeat cycle time and thus has to be higher than the corresponding producer heartbeat time configured on the device producing this heartbeat. Bits 31 - 24 of each sub-index must be 0. Bits 23 - 16 contain the node-ID. The lower 16 bits contain the heartbeat time.
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned32

**Entry Description**

<b>Sub-Index</b>	000
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<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x2
<b>Lower Limit</b>	0x1
<b>Upper Limit</b>	0x7F

---

<b>Sub-Index</b>	001
<b>Description</b>	Consumer Heartbeat Time 1
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x2FFFFFF

---



<b>Sub-Index</b>	002
<b>Description</b>	Consumer Heartbeat Time 2
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x2FFFFFFF

## 1017h – Producer Heartbeat Time

### Object Description

<b>Index</b>	1017
<b>Description</b>	This object defines the cycle time of the heartbeat. If its value is 0 it is not used. The time must be a multiple of 1 millisecond.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x000007D0
<b>Unit</b>	1 millisecond (ms)
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFF

## 1018h – Identity Object

### Object Description

<b>Index</b>	1018
<b>Description</b>	This object contains general information about the device. Sub-index 1 contains a unique value allocated each manufacturer. Sub-index 2 defines the manufacturer specific product code (device version). Sub-index 3 defines the revision number. Bit 31-16 is the major revision number Bit 15-0 the minor revision number. Sub-index 4 defines a manufacturer specific serial number.

<b>Object Code</b>	Record
<b>Data Type</b>	IDENTITY

**Entry Description**

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x4
<b>Lower Limit</b>	0x1
<b>Upper Limit</b>	0x4

<b>Sub-Index</b>	001
<b>Description</b>	Vendor Id
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x02e1
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Product Code
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xA5A5
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	003
<b>Description</b>	Revision number
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	004
<b>Description</b>	Serial number
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 1200h – Server SDO Parameter 1

### Object Description

<b>Index</b>	1200
<b>Description</b>	The object contains the parameters for the SDOs for which the device is the server.
<b>Object Code</b>	Record
<b>Data Type</b>	SDO_PARAMETER

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x02
<b>Lower Limit</b>	0x02
<b>Upper Limit</b>	0x02

---

<b>Sub-Index</b>	001
<b>Description</b>	COB-ID Client -> Server
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000600
<b>Lower Limit</b>	0x00000600
<b>Upper Limit</b>	0xBFFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	COB-ID Server -> Client
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000580
<b>Lower Limit</b>	0x00000580
<b>Upper Limit</b>	0xBFFFFFFF

## 1400h – Receive PDO Communication Parameter 1

### Object Description

<b>Index</b>	1400
<b>Description</b>	<p>The object contains the communication parameters for the PDOs that the device is able to receive.</p> <p>Sub-index 0 defines the number of PDO-parameters implemented.</p> <p>Sub-index 1 defines the COB-ID. If bit 31 is set, the PDO is disabled.</p> <p>Sub-index 2 defines the transmission type.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_COMM_PAR

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x02
<b>Lower Limit</b>	0x2
<b>Upper Limit</b>	0x5

<b>Sub-Index</b>	001
<b>Description</b>	COB-ID
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x200
<b>Lower Limit</b>	0x1
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Transmission Type
<b>Data Type</b>	Unsigned8
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x1
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFF

## 1401h – Receive PDO Communication Parameter 2

### Object Description

<b>Index</b>	1401
<b>Description</b>	<p>The object contains the communication parameters for the PDOs that the device is able to receive.</p> <p>Sub-index 0 defines the number of PDO-parameters implemented.</p> <p>Sub-index 1 defines the COB-ID. If bit 31 is set, the PDO is disabled.</p> <p>Sub-index 2 defines the transmission type.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_COMM_PAR

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x02
<b>Lower Limit</b>	0x02
<b>Upper Limit</b>	0x05

<b>Sub-Index</b>	001
<b>Description</b>	COB-ID
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000300
<b>Lower Limit</b>	0x00000001
<b>Upper Limit</b>	0xFFFFFFFF



<b>Sub-Index</b>	002
<b>Description</b>	Transmission Type
<b>Data Type</b>	Unsigned8
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x1
<b>Lower Limit</b>	0x00
<b>Upper Limit</b>	0xFF

## 1402h – Receive PDO Communication Parameter 3

### Object Description

<b>Index</b>	1402
<b>Description</b>	<p>The object contains the communication parameters for the PDOs that the device is able to receive.</p> <p>Sub-index 0 defines the number of PDO-parameters implemented.</p> <p>Sub-index 1 defines the COB-ID. If bit 31 is set, the PDO is disabled.</p> <p>Sub-index 2 defines the transmission type.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_COMM_PAR

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x02
<b>Lower Limit</b>	0x02
<b>Upper Limit</b>	0x05

<b>Sub-Index</b>	001
<b>Description</b>	COB-ID
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000400
<b>Lower Limit</b>	0x00000001
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Transmission Type
<b>Data Type</b>	Unsigned8
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x1
<b>Lower Limit</b>	0x00
<b>Upper Limit</b>	0xFF

## 1403h – Receive PDO Communication Parameter 4

### Object Description

<b>Index</b>	1403
<b>Description</b>	<p>The object contains the communication parameters for the PDOs that the device is able to receive.</p> <p>Sub-index 0 defines the number of PDO-parameters implemented.</p> <p>Sub-index 1 defines the COB-ID. If bit 31 is set, the PDO is disabled.</p> <p>Sub-index 2 defines the transmission type.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_COMM_PAR

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x02
<b>Lower Limit</b>	0x02
<b>Upper Limit</b>	0x05

<b>Sub-Index</b>	001
<b>Description</b>	COB-ID
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000500
<b>Lower Limit</b>	0x00000001
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Transmission Type
<b>Data Type</b>	Unsigned8
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xFF
<b>Lower Limit</b>	0x00
<b>Upper Limit</b>	0xFF

## 1404h – Receive PDO Communication Parameter 5

### Object Description

<b>Index</b>	1404
<b>Description</b>	<p>The object contains the communication parameters for the PDOs that the device is able to receive.</p> <p>Sub-index 0 defines the number of PDO-parameters implemented.</p> <p>Sub-index 1 defines the COB-ID. If bit 31 is set, the PDO is disabled.</p> <p>Sub-index 2 defines the transmission type.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_COMM_PAR

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x02
<b>Lower Limit</b>	0x02
<b>Upper Limit</b>	0x05

<b>Sub-Index</b>	001
<b>Description</b>	COB-ID
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000500
<b>Lower Limit</b>	0x00000001
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Transmission Type
<b>Data Type</b>	Unsigned8
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xFF
<b>Lower Limit</b>	0x00
<b>Upper Limit</b>	0xFF

## 1405h – Receive PDO Communication Parameter 6

### Object Description

<b>Index</b>	1405
<b>Description</b>	<p>The object contains the communication parameters for the PDOs that the device is able to receive.</p> <p>Sub-index 0 defines the number of PDO-parameters implemented.</p> <p>Sub-index 1 defines the COB-ID. If bit 31 is set, the PDO is disabled.</p> <p>Sub-index 2 defines the transmission type.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_COMM_PAR

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x02
<b>Lower Limit</b>	0x02
<b>Upper Limit</b>	0x05

<b>Sub-Index</b>	001
<b>Description</b>	COB-ID
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000500
<b>Lower Limit</b>	0x00000001
<b>Upper Limit</b>	0xFFFFFFFF



<b>Sub-Index</b>	002
<b>Description</b>	Transmission Type
<b>Data Type</b>	Unsigned8
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xFF
<b>Lower Limit</b>	0x00
<b>Upper Limit</b>	0xFF

## 1406h – Receive PDO Communication Parameter 7

### Object Description

<b>Index</b>	1406
<b>Description</b>	<p>The object contains the communication parameters for the PDOs that the device is able to receive.</p> <p>Sub-index 0 defines the number of PDO-parameters implemented.</p> <p>Sub-index 1 defines the COB-ID. If bit 31 is set, the PDO is disabled.</p> <p>Sub-index 2 defines the transmission type.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_COMM_PAR

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x02
<b>Lower Limit</b>	0x02
<b>Upper Limit</b>	0x05

<b>Sub-Index</b>	001
<b>Description</b>	COB-ID
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000500
<b>Lower Limit</b>	0x00000001
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Transmission Type
<b>Data Type</b>	Unsigned8
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xFF
<b>Lower Limit</b>	0x00
<b>Upper Limit</b>	0xFF

## 1407h – Receive PDO Communication Parameter 8

### Object Description

<b>Index</b>	1407
<b>Description</b>	<p>The object contains the communication parameters for the PDOs that the device is able to receive.</p> <p>Sub-index 0 defines the number of PDO-parameters implemented.</p> <p>Sub-index 1 defines the COB-ID. If bit 31 is set, the PDO is disabled.</p> <p>Sub-index 2 defines the transmission type.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_COMM_PAR

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x02
<b>Lower Limit</b>	0x02
<b>Upper Limit</b>	0x05

<b>Sub-Index</b>	001
<b>Description</b>	COB-ID
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000500
<b>Lower Limit</b>	0x00000001
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Transmission Type
<b>Data Type</b>	Unsigned8
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xFF
<b>Lower Limit</b>	0x00
<b>Upper Limit</b>	0xFF

## 1600h – Receive PDO Mapping Parameter 1

### Object Description

<b>Index</b>	1600
<b>Description</b>	<p>This object contains the mapping for the PDOs the device is able to receive.</p> <p>Sub-index 0 defines the number of valid entries in the mapping record. This Number of entries is also the number of the application variables that are received with the corresponding PDO.</p> <p>Sub-indexes 1 to number of mapped entries contain information about the mapped application variables. These entries describe the PDO contents by their index, sub-index and length. All three values are hexadecimal coded. The length entry defines the length of the object in bits.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_MAPPING

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x02
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x40

---

<b>Sub-Index</b>	001
<b>Description</b>	Mapping Entry 1
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x60400010
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Mapping Entry 2
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x60600008
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	003
<b>Description</b>	Mapping Entry 3
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	004
<b>Description</b>	Mapping Entry 4
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 1601h – Receive PDO Mapping Parameter 2

### Object Description

<b>Index</b>	1601
<b>Description</b>	<p>This object contains the mapping for the PDOs the device is able to receive.</p> <p>Sub-index 0 defines the number of valid entries in the mapping record. This Number of entries is also the number of the application variables that are received with the corresponding PDO.</p> <p>Sub-indexes 1 to number of mapped entries contain information about the mapped application variables. These entries describe the PDO contents by their index, sub-index and length. All three values are hexadecimal coded. The length entry defines the length of the object in bits.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_MAPPING

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x02
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x40

---

<b>Sub-Index</b>	001
<b>Description</b>	Mapping Entry 1
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x607A0020
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Mapping Entry 2
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x60810020
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	003
<b>Description</b>	Mapping Entry 3
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---



<b>Sub-Index</b>	004
<b>Description</b>	Mapping Entry 4
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 1602h – Receive PDO Mapping Parameter 3

### Object Description

<b>Index</b>	1602
<b>Description</b>	<p>This object contains the mapping for the PDOs the device is able to receive.</p> <p>Sub index 0 defines the number of valid entries in the mapping record. This Number of entries is also the number of the application variables that are received with the corresponding PDO.</p> <p>Sub indexes 1 to number of mapped entries contain information about the mapped application variables. These entries describe the PDO contents by their index, sub index and length. All three values are hexadecimal coded. The length entry defines the length of the object in bits.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_MAPPING

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x02
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x40

---

<b>Sub-Index</b>	001
<b>Description</b>	Mapping Entry 1
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x60710010
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Mapping Entry 2
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x60FF0020
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	003
<b>Description</b>	Mapping Entry 3
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	004
<b>Description</b>	Mapping Entry 4
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 1603h – Receive PDO Mapping Parameter 4

### Object Description

<b>Index</b>	1603
<b>Description</b>	<p>This object contains the mapping for the PDOs the device is able to receive.</p> <p>Sub-index 0 defines the number of valid entries in the mapping record. This Number of entries is also the number of the application variables that are received with the corresponding PDO.</p> <p>Sub-indexes 1 to number of mapped entries contain information about the mapped application variables. These entries describe the PDO contents by their index, sub-index and length. All three values are hexadecimal coded. The length entry defines the length of the object in bits.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_MAPPING

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x01
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x40

---

<b>Sub-Index</b>	001
<b>Description</b>	Mapping Entry 1
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x20070020
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Mapping Entry 2
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	003
<b>Description</b>	Mapping Entry 3
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	004
<b>Description</b>	Mapping Entry 4
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 1604h – Receive PDO Mapping Parameter 5

### Object Description

<b>Index</b>	1604
<b>Description</b>	<p>This object contains the mapping for the PDOs the device is able to receive.</p> <p>Sub-index 0 defines the number of valid entries in the mapping record. This Number of entries is also the number of the application variables that are received with the corresponding PDO.</p> <p>Sub-indexes from 1 to the number of mapped entries contain information about the mapped application variables. These entries describe the PDO contents by their index, sub-index and length. All three values are hexadecimal coded. The length entry defines the length of the object in bits.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_MAPPING

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x40

---

<b>Sub-Index</b>	001
<b>Description</b>	Mapping Entry 1
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Mapping Entry 2
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	003
<b>Description</b>	Mapping Entry 3
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	004
<b>Description</b>	Mapping Entry 4
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 1605h – Receive PDO Mapping Parameter 6

### Object Description

<b>Index</b>	1605
<b>Description</b>	<p>This object contains the mapping for the PDOs the device is able to receive.</p> <p>Sub-index 0 defines the number of valid entries in the mapping record. This Number of entries is also the number of the application variables that are received with the corresponding PDO.</p> <p>Sub-indexes from 1 to the number of mapped entries contain information about the mapped application variables. These entries describe the PDO contents by their index, sub-index and length. All three values are hexadecimal coded. The length entry defines the length of the object in bits.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_MAPPING

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x40

---

<b>Sub-Index</b>	001
<b>Description</b>	Mapping Entry 1
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Mapping Entry 2
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	003
<b>Description</b>	Mapping Entry 3
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---



<b>Sub-Index</b>	004
<b>Description</b>	Mapping Entry 4
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 1606h – Receive PDO Mapping Parameter 7

### Object Description

<b>Index</b>	1606
<b>Description</b>	<p>This object contains the mapping for the PDOs the device is able to receive.</p> <p>Sub-index 0 defines the number of valid entries in the mapping record. This Number of entries is also the number of the application variables that are received with the corresponding PDO.</p> <p>Sub-indexes from 1 to the number of mapped entries contain information about the mapped application variables. These entries describe the PDO contents by their index, sub-index and length. All three values are hexadecimal coded. The length entry defines the length of the object in bits.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_MAPPING

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x40

---

<b>Sub-Index</b>	001
<b>Description</b>	Mapping Entry 1
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Mapping Entry 2
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	003
<b>Description</b>	Mapping Entry 3
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	004
<b>Description</b>	Mapping Entry 4
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 1607h – Receive PDO Mapping Parameter 8

### Object Description

<b>Index</b>	1607
<b>Description</b>	<p>This object contains the mapping for the PDOs the device is able to receive.</p> <p>Sub-index 0 defines the number of valid entries in the mapping record. This Number of entries is also the number of the application variables that are received with the corresponding PDO.</p> <p>Sub-indexes from 1 to the number of mapped entries contain information about the mapped application variables. These entries describe the PDO contents by their index, sub-index and length. All three values are hexadecimal coded. The length entry defines the length of the object in bits.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_MAPPING

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x40

---

<b>Sub-Index</b>	001
<b>Description</b>	Mapping Entry 1
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Mapping Entry 2
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	003
<b>Description</b>	Mapping Entry 3
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	004
<b>Description</b>	Mapping Entry 4
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 1800h – Transmit PDO Communication Parameter 1

### Object Description

<b>Index</b>	1800
<b>Description</b>	Contains the communication parameters of the current PDO the device is able to transmit. Sub-index 0 defines the number of PDO parameters implemented. Sub-index 1 describes the COB ID. If bit 31 is set, the PDO is disabled. Sub-index 2 defines the transmission type.
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_COMM_PAR

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x03
<b>Lower Limit</b>	0x02
<b>Upper Limit</b>	0x06

---

<b>Sub-Index</b>	001
<b>Description</b>	COB-ID
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x180
<b>Lower Limit</b>	0x1
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Transmission Type
<b>Data Type</b>	Unsigned8
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xFF
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFF

---

<b>Sub-Index</b>	003
<b>Description</b>	Inhibit Time
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x7D0
<b>Unit</b>	100 us
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0xFFFF

## 1801h – Transmit PDO Communication Parameter 2

### Object Description

<b>Index</b>	1801
<b>Description</b>	Contains the communication parameters of the current PDO the device is able to transmit. Sub-index 0 defines the number of PDO parameters implemented. Sub-index 1 describes the COB ID. If bit 31 is set, the PDO is disabled. Sub-index 2 defines the transmission type.
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_COMM_PAR

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x03
<b>Lower Limit</b>	0x02
<b>Upper Limit</b>	0x06

---

<b>Sub-Index</b>	001
<b>Description</b>	COB-ID
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000280
<b>Lower Limit</b>	0x00000001
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Transmission Type
<b>Data Type</b>	Unsigned8
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xFF
<b>Lower Limit</b>	0x00
<b>Upper Limit</b>	0xFF

---



<b>Sub-Index</b>	003
<b>Description</b>	Inhibit Time
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x7D0
<b>Unit</b>	100 us
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0xFFFF

## 1802h – Transmit PDO Communication Parameter 3

### Object Description

<b>Index</b>	1802
<b>Description</b>	Contains the communication parameters of the current PDO the device is able to transmit. Sub-index 0 defines the number of PDO parameters implemented. Sub-index 1 describes the COB ID. If bit 31 is set, the PDO is disabled. Sub-index 2 defines the transmission type.
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_COMM_PAR

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x03
<b>Lower Limit</b>	0x02
<b>Upper Limit</b>	0x06

---

<b>Sub-Index</b>	001
<b>Description</b>	COB-ID
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000380
<b>Lower Limit</b>	0x00000001
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Transmission Type
<b>Data Type</b>	Unsigned8
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xFF
<b>Lower Limit</b>	0x00
<b>Upper Limit</b>	0xFF

---

<b>Sub-Index</b>	003
<b>Description</b>	Inhibit Time
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x7D0
<b>Unit</b>	100 us
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0xFFFF

## 1803h – Transmit PDO Communication Parameter 4

### Object Description

<b>Index</b>	1803
<b>Description</b>	Contains the communication parameters of the current PDO the device is able to transmit. Sub-index 0 defines the number of PDO parameters implemented. Sub-index 1 describes the COB ID. If bit 31 is set, the PDO is disabled. Sub-index 2 defines the transmission type.
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_COMM_PAR

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x03
<b>Lower Limit</b>	0x02
<b>Upper Limit</b>	0x06

---

<b>Sub-Index</b>	001
<b>Description</b>	COB-ID
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000480
<b>Lower Limit</b>	0x00000001
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Transmission Type
<b>Data Type</b>	Unsigned8
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xFF
<b>Lower Limit</b>	0x00
<b>Upper Limit</b>	0xFF

---

<b>Sub-Index</b>	003
<b>Description</b>	Inhibit Time
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x7D0
<b>Unit</b>	100 us
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0xFFFF

## 1804h – Transmit PDO Communication Parameter 5

### Object Description

<b>Index</b>	1804
<b>Description</b>	Contains the communication parameters of the current PDO the device is able to transmit. Sub-index 0 defines the number of PDO parameters implemented. Sub-index 1 describes the COB ID. If bit 31 is set, the PDO is disabled. Sub-index 2 defines the transmission type.
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_COMM_PAR

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x03
<b>Lower Limit</b>	0x02
<b>Upper Limit</b>	0x06

---

<b>Sub-Index</b>	001
<b>Description</b>	COB-ID
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000480
<b>Lower Limit</b>	0x00000001
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Transmission Type
<b>Data Type</b>	Unsigned8
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xFF
<b>Lower Limit</b>	0x00
<b>Upper Limit</b>	0xFF

---

<b>Sub-Index</b>	003
<b>Description</b>	Inhibit Time
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x7D0
<b>Unit</b>	100 us
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0xFFFF

## 1805h – Transmit PDO Communication Parameter 6

### Object Description

<b>Index</b>	1805
<b>Description</b>	Contains the communication parameters of the current PDO the device is able to transmit. Sub-index 0 defines the number of PDO parameters implemented. Sub-index 1 describes the COB ID. If bit 31 is set, the PDO is disabled. Sub-index 2 defines the transmission type.
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_COMM_PAR

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x03
<b>Lower Limit</b>	0x02
<b>Upper Limit</b>	0x06

---

<b>Sub-Index</b>	001
<b>Description</b>	COB-ID
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000480
<b>Lower Limit</b>	0x00000001
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Transmission Type
<b>Data Type</b>	Unsigned8
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xFF
<b>Lower Limit</b>	0x00
<b>Upper Limit</b>	0xFF

---



<b>Sub-Index</b>	003
<b>Description</b>	Inhibit Time
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x7D0
<b>Unit</b>	100 us
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0xFFFF

## 1806h – Transmit PDO Communication Parameter 7

### Object Description

<b>Index</b>	1806
<b>Description</b>	Contains the communication parameters of the current PDO the device is able to transmit. Sub-index 0 defines the number of PDO parameters implemented. Sub-index 1 describes the COB ID. If bit 31 is set, the PDO is disabled. Sub-index 2 defines the transmission type.
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_COMM_PAR

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x03
<b>Lower Limit</b>	0x02
<b>Upper Limit</b>	0x06

---

<b>Sub-Index</b>	001
<b>Description</b>	COB-ID
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000480
<b>Lower Limit</b>	0x00000001
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Transmission Type
<b>Data Type</b>	Unsigned8
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xFF
<b>Lower Limit</b>	0x00
<b>Upper Limit</b>	0xFF

---

<b>Sub-Index</b>	003
<b>Description</b>	Inhibit Time
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x7D0
<b>Unit</b>	100 us
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0xFFFF

## 1807h – Transmit PDO Communication Parameter 8

### Object Description

<b>Index</b>	1807
<b>Description</b>	Contains the communication parameters of the current PDO the device is able to transmit. Sub-index 0 defines the number of PDO parameters implemented. Sub-index 1 describes the COB ID. If bit 31 is set, the PDO is disabled. Sub-index 2 defines the transmission type.
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_COMM_PAR

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x03
<b>Lower Limit</b>	0x02
<b>Upper Limit</b>	0x06

---

<b>Sub-Index</b>	001
<b>Description</b>	COB-ID
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000480
<b>Lower Limit</b>	0x00000001
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Transmission Type
<b>Data Type</b>	Unsigned8
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xFF
<b>Lower Limit</b>	0x00
<b>Upper Limit</b>	0xFF

---

<b>Sub-Index</b>	003
<b>Description</b>	Inhibit Time
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x7D0
<b>Unit</b>	100 us
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0xFFFF

## 1A00h – Transmit PDO Mapping Parameter 1

### Object Description

<b>Index</b>	1A00
<b>Description</b>	<p>Contains the mapping for the PDOs the device is able to transmit.</p> <p>Sub-index 0 defines the number of valid entries in the mapping record. This Number of entries is also the number of the application variables that are transmitted with the corresponding PDO.</p> <p>Sub-indexes 1 to Number of entries: Contain information about the mapped application variables.</p> <p>These entries describe the PDO contents by their index, sub-index and length. All three values are hexadecimal coded. The length entry defines the length of the object in bits.</p> <p>The type of the PDO mapping parameter is at index 21h.</p> <p>This parameter can be used to verify the overall mapping length. It is mandatory.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_MAPPING

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x02
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFF

---

<b>Sub-Index</b>	001
<b>Description</b>	Mapping Entry 1
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x60410010
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Mapping Entry 2
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x60610008
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	003
<b>Description</b>	Mapping Entry 3
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	004
<b>Description</b>	Mapping Entry 4
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

## 1A01h – Transmit PDO Mapping Parameter 2

### Object Description

<b>Index</b>	1A01
<b>Description</b>	<p>Contains the mapping for the PDOs the device is able to transmit.</p> <p>Sub-index 0 defines the number of valid entries in the mapping record. This Number of entries is also the number of the application variables that are transmitted with the corresponding PDO.</p> <p>Sub-indexes 1 to Number of entries: Contain information about the mapped application variables.</p> <p>These entries describe the PDO contents by their index, sub-index and length. All three values are hexadecimal coded. The length entry defines the length of the object in bits.</p> <p>The type of the PDO mapping parameter is at index 21h.</p> <p>This parameter can be used to verify the overall mapping length. It is mandatory.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_MAPPING

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x02
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFF

---

<b>Sub-Index</b>	001
<b>Description</b>	Mapping Entry 1
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x60640020
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Mapping Entry 2
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x606C0020
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	003
<b>Description</b>	Mapping Entry 3
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

---



<b>Sub-Index</b>	004
<b>Description</b>	Mapping Entry 4
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

## 1A02h – Transmit PDO Mapping Parameter 3

### Object Description

<b>Index</b>	1A02
<b>Description</b>	<p>Contains the mapping for the PDOs the device is able to transmit.</p> <p>Sub-index 0 defines the number of valid entries in the mapping record. This Number of entries is also the number of the application variables that are transmitted with the corresponding PDO.</p> <p>Sub-indexes 1 to Number of entries: Contain information about the mapped application variables.</p> <p>These entries describe the PDO contents by their index, sub-index and length. All three values are hexadecimal coded. The length entry defines the length of the object in bits.</p> <p>The type of the PDO mapping parameter is at index 21h.</p> <p>This parameter can be used to verify the overall mapping length. It is mandatory.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_MAPPING

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x03
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFF

---

<b>Sub-Index</b>	001
<b>Description</b>	Mapping Entry 1
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x60780010
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Mapping Entry 2
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x60740010
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

---

<b>Sub-Index</b>	003
<b>Description</b>	Mapping Entry 3
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x606B0020
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

---

<b>Sub-Index</b>	004
<b>Description</b>	Mapping Entry 4
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

## 1A03h – Transmit PDO Mapping Parameter 4

### Object Description

<b>Index</b>	1A03
<b>Description</b>	<p>Contains the mapping for the PDOs the device is able to transmit.</p> <p>Sub-index 0 defines the number of valid entries in the mapping record. This Number of entries is also the number of the application variables that are transmitted with the corresponding PDO.</p> <p>Sub-indexes 1 to Number of entries: Contain information about the mapped application variables.</p> <p>These entries describe the PDO contents by their index, sub-index and length. All three values are hexadecimal coded. The length entry defines the length of the object in bits.</p> <p>The type of the PDO mapping parameter is at index 21h.</p> <p>This parameter can be used to verify the overall mapping length. It is mandatory.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_MAPPING

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x01
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFF

---

<b>Sub-Index</b>	001
<b>Description</b>	Mapping Entry 1
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x60FA0020
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Mapping Entry 2
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x60F40020
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

---

<b>Sub-Index</b>	003
<b>Description</b>	Mapping Entry 3
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

---

<b>Sub-Index</b>	004
<b>Description</b>	Mapping Entry 4
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

## 1A04h – Transmit PDO Mapping Parameter 5

### Object Description

<b>Index</b>	1A04
<b>Description</b>	<p>Contains the mapping for the PDOs the device is able to transmit.</p> <p>Sub-index 0 defines the number of valid entries in the mapping record. This Number of entries is also the number of the application variables that are transmitted with the corresponding PDO.</p> <p>Sub-indexes 1 to Number of entries: Contain information about the mapped application variables.</p> <p>These entries describe the PDO contents by their index, sub-index and length. All three values are hexadecimal coded. The length entry defines the length of the object in bits.</p> <p>The type of the PDO mapping parameter is at index 21h.</p> <p>This parameter can be used to verify the overall mapping length. It is mandatory.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_MAPPING

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFF

---

<b>Sub-Index</b>	001
<b>Description</b>	Mapping Entry 1
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Mapping Entry 2
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	003
<b>Description</b>	Mapping Entry 3
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

---

<b>Sub-Index</b>	004
<b>Description</b>	Mapping Entry 4
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

## 1A05h – Transmit PDO Mapping Parameter 6

### Object Description

<b>Index</b>	1A05
<b>Description</b>	<p>Contains the mapping for the PDOs the device is able to transmit.</p> <p>Sub-index 0 defines the number of valid entries in the mapping record. This Number of entries is also the number of the application variables that are transmitted with the corresponding PDO.</p> <p>Sub-indexes 1 to Number of entries: Contain information about the mapped application variables.</p> <p>These entries describe the PDO contents by their index, sub-index and length. All three values are hexadecimal coded. The length entry defines the length of the object in bits.</p> <p>The type of the PDO mapping parameter is at index 21h.</p> <p>This parameter can be used to verify the overall mapping length. It is mandatory.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_MAPPING

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFF

---

<b>Sub-Index</b>	001
<b>Description</b>	Mapping Entry 1
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Mapping Entry 2
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

---

<b>Sub-Index</b>	003
<b>Description</b>	Mapping Entry 3
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

---



<b>Sub-Index</b>	004
<b>Description</b>	Mapping Entry 4
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

## 1A06h – Transmit PDO Mapping Parameter 7

### Object Description

<b>Index</b>	1A06
<b>Description</b>	<p>Contains the mapping for the PDOs the device is able to transmit.</p> <p>Sub-index 0 defines the number of valid entries in the mapping record. This Number of entries is also the number of the application variables that are transmitted with the corresponding PDO.</p> <p>Sub-indexes 1 to Number of entries: Contain information about the mapped application variables.</p> <p>These entries describe the PDO contents by their index, sub-index and length. All three values are hexadecimal coded. The length entry defines the length of the object in bits.</p> <p>The type of the PDO mapping parameter is at index 21h.</p> <p>This parameter can be used to verify the overall mapping length. It is mandatory.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_MAPPING

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFF

---

<b>Sub-Index</b>	001
<b>Description</b>	Mapping Entry 1
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Mapping Entry 2
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

---

<b>Sub-Index</b>	003
<b>Description</b>	Mapping Entry 3
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

---

<b>Sub-Index</b>	004
<b>Description</b>	Mapping Entry 4
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

## 1A07h – Transmit PDO Mapping Parameter 8

### Object Description

<b>Index</b>	1A07
<b>Description</b>	<p>Contains the mapping for the PDOs the device is able to transmit.</p> <p>Sub-index 0 defines the number of valid entries in the mapping record. This Number of entries is also the number of the application variables that are transmitted with the corresponding PDO.</p> <p>Sub-indexes 1 to Number of entries: Contain information about the mapped application variables.</p> <p>These entries describe the PDO contents by their index, sub-index and length. All three values are hexadecimal coded. The length entry defines the length of the object in bits.</p> <p>The type of the PDO mapping parameter is at index 21h.</p> <p>This parameter can be used to verify the overall mapping length. It is mandatory.</p>
<b>Object Code</b>	Record
<b>Data Type</b>	PDO_MAPPING

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFF

---

<b>Sub-Index</b>	001
<b>Description</b>	Mapping Entry 1
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Mapping Entry 2
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

---

<b>Sub-Index</b>	003
<b>Description</b>	Mapping Entry 3
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

---

<b>Sub-Index</b>	004
<b>Description</b>	Mapping Entry 4
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000000
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

---

## 3 Manufacturer Segment

### 2006h – Current Integral Gain

#### Object Description

<b>Index</b>	2006
<b>Description</b>	This object indicates the current controller integral gain.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

#### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x7D0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

### 2007h – Current Proportional Gain

#### Object Description

<b>Index</b>	2007
<b>Description</b>	This object indicates the current controller proportional gain.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

#### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x9C40
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

### 2011h – Warning bits

#### Object Description

<b>Index</b>	2011
<b>Description</b>	This object logs the drive warnings. To clear the warnings, set fault reset bit (#7) in Controlword. The bits have the following meaning: bit 1: CW limit switch on bit 2: CCW limit switch on bit 3: Encoder sensor detected disturbance in the force
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x00
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

**201Eh – Position Derivative Gain****Object Description**

<b>Index</b>	201E
<b>Description</b>	This object indicates the position derivative gain.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

**2020h – Position Integral Gain****Object Description**

<b>Index</b>	2020
<b>Description</b>	This object indicates the position integral gain.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

**2022h – Position Proportional Gain****Object Description**

<b>Index</b>	2022
<b>Description</b>	This object indicates the position proportional gain.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x2710
<b>Unit</b>	RPM/100/Encoder Counts/2 <sup>16</sup>
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

**2023h – Position Velocity Feedforward Gain****Object Description**

<b>Index</b>	2023
<b>Description</b>	This object indicates the velocity feed forward gain.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x100
<b>Unit</b>	RPM/256
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

## 2026h – Velocity Integral Gain

### Object Description

<b>Index</b>	2026
<b>Description</b>	This object indicates the velocity integral gain.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x5
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x1000000

## 2027h – Velocity Proportional Gain

### Object Description

<b>Index</b>	2027
<b>Description</b>	This object indicates the velocity proportional gain.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x1388
<b>Unit</b>	mA/(RPM/100) /2 <sup>16</sup>
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x1000000

## 2028h – Mechanical Position

### Object Description

<b>Index</b>	2028
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<b>Description</b>	This object indicates the mechanical angle position in 16-bit resolution. It gets the position (angle) of the motor shaft within one mechanical motor revolution. The mechanical angle position increments from 0 to 65535 in the course of one mechanical motor shaft revolution (360 degrees). The range of the mechanical angle position does not change. Its resolution is dependent upon the feedback device resolution. (mechanical angle position)/65535 * 360 = Angle [degrees]
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Unit</b>	360/2 <sup>16</sup> deg
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFF

**2033h – I2T Value****Object Description**

<b>Index</b>	2033
<b>Description</b>	This object indicates the current I2T value. It is calculated by integrating [actual current (object 6078h) - rated current (object 6075h)] to the second power, over time. Fault condition occurs when the I2T value (object 2033h) exceeds I2T Fault Threshold (object 2034h)
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Unit</b>	ampere <sup>2</sup> *millisecond(ms)
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

**2034h – I2T Fault Threshold**

**Object Description**

<b>Index</b>	2034
<b>Description</b>	This object indicates the threshold for I2T fault. Setting it to zero disables this function.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	ampere^2*millisecond(ms)
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

**2036h – Peak Current****Object Description**

<b>Index</b>	2036
<b>Description</b>	This object indicates the peak rated current.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x1770
<b>Unit</b>	milliampere
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

**2043h – Commutation Offset****Object Description**

<b>Index</b>	2043
<b>Description</b>	This object indicates the encoder phase relative to the standard commutation table.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x5A
<b>Unit</b>	Degree
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x168

**2044h – Drive Temperature**

This object indicates the temperature of the drive electronics board (Celsius degrees).

**Object Description**

<b>Index</b>	2044
<b>Description</b>	Drive Temperature
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Unit</b>	degree Celsius
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

**2045h – Feedback Direction****Object Description**

<b>Index</b>	2045
<b>Description</b>	This object indicates the feedback positive direction. 1 = CW is considered positive 0 = CCW is considered positive
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer8

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x01
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x00
<b>Upper Limit</b>	0x01

**204Ch – Factory Restore****Object Description**

<b>Index</b>	204C
<b>Description</b>	This object restores all configuration variables to factory default settings. Writing 0x64616F6C (ASCII "load") initiates the factory restore command.

<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

**204Dh – Feedback Type****Object Description**

<b>Index</b>	204D
<b>Description</b>	This object indicates the type of motor feedback. 1 = Absolute single turn encoder
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x1
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x1
<b>Upper Limit</b>	0x1

**2070h – Digital Inputs Polarity****Object Description**

<b>Index</b>	2070
<b>Description</b>	This object inverts the polarity of each digital input. 0 = Polarity inverted 1 = Polarity not inverted
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned16

**Entry Description**

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x4
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x4

<b>Sub-Index</b>	001
<b>Description</b>	Polarity of Input Number 1
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x1
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x1

<b>Sub-Index</b>	002
<b>Description</b>	Polarity of Input Number 2
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x1
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x1

<b>Sub-Index</b>	003
<b>Description</b>	Polarity of Input Number 3
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x1
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x1

<b>Sub-Index</b>	004
<b>Description</b>	Polarity of Input Number 4
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x1
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x1

## 2072h – Phase A Actual Current

### Object Description

<b>Index</b>	2072
<b>Description</b>	This object indicates the actual current at phase A.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0000
<b>Unit</b>	milliampere
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

## 2073h – Phase A Current Offset 1

### Object Description

<b>Index</b>	2073
<b>Description</b>	This object indicates the current offset of phase A.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0xF801
<b>Unit</b>	milliampere
<b>Lower Limit</b>	0x8000

<b>Upper Limit</b>	0x7FFF
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## 2074h – Phase B Actual Current

### Object Description

<b>Index</b>	2074
<b>Description</b>	This object indicates the actual current at phase B.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0000
<b>Unit</b>	milliampere
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

## 2075h – Phase B Current Offset 1

### Object Description

<b>Index</b>	2075
<b>Description</b>	This object indicates the current offset of phase B.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0xF801
<b>Unit</b>	milliampere
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

## 2076h – Phase A Current Offset 2

### Object Description

<b>Index</b>	2076
<b>Description</b>	This object indicates the current offset of phase A.
<b>Object Code</b>	Variable



<b>Data Type</b>	Integer16
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**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0xF801
<b>Unit</b>	milliampere
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

**2077h – Position Integral Input Saturation****Object Description**

<b>Index</b>	2077
<b>Description</b>	This object indicates the position integral input saturation.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x186A0
<b>Unit</b>	counts
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

**2078h – Phase B Current Offset 2****Object Description**

<b>Index</b>	2078
<b>Description</b>	This object indicates the current offset of phase B.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0xF801
<b>Unit</b>	milliampere

<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

## 207Dh – Motor Pitch

### Object Description

<b>Index</b>	207D
<b>Description</b>	This object indicates the pitch of a linear motor.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x800
<b>Unit</b>	mm
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 207Eh – Motor Poles

### Object Description

<b>Index</b>	207E
<b>Description</b>	This object indicates the number of individual poles (not pairs) in the motor.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0064
<b>Lower Limit</b>	0x0002
<b>Upper Limit</b>	0x0190

## 2090h – Home Status

### Object Description

<b>Index</b>	2090
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<b>Description</b>	This object indicates the status of the homing procedure. 0 = Not Homed 1 = Homed 2 = Failed
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

**2099h – Current Level 1 for Digital Output Definition****Object Description**

<b>Index</b>	2099
<b>Description</b>	The value of this object is used by the Digital Outputs Functionality object (209Ch) as the first current value for a condition that controls a digital output.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	milliampere
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x2EE0

**209Ah – Current Level 2 for Digital Output Definition****Object Description**

<b>Index</b>	209A
<b>Description</b>	The value of this object is used by the Digital Outputs Functionality object (209Ch) as the second current value for a condition that controls a digital output.

<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x2EE0
<b>Unit</b>	milliampere
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x2EE0

**209Bh – Digital Outputs Polarity****Object Description**

<b>Index</b>	209B
<b>Description</b>	This object inverts the polarity of each digital output. 0 = Polarity not inverted 1 = Polarity inverted
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned16

**Entry Description**

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x2
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x2

<b>Sub-Index</b>	001
<b>Description</b>	Polarity of Output Number 1
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x1

<b>Sub-Index</b>	002
<b>Description</b>	Polarity of Output Number 2
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x1

## 209Ch – Digital Output Functionality

### Object Description

<b>Index</b>	209C
<b>Description</b>	<p>This object defines the function of each digital output.</p> <p>0 = Disabled  1 = Motor Speed Set  2 = Current  3 = Reserved1  4 = Motor Speed Set Clear  5 = Over Voltage  6 = Motion Completed  7 = In Position  8 = Zero Speed  9 = Limit Switch  10 = Active  11 = Reserved2  12 = Reserved3  13 = User</p>
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned16

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x2
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x2

<b>Sub-Index</b>	001
<b>Description</b>	Functionality of Output Number 1
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xD

<b>Sub-Index</b>	002
<b>Description</b>	Functionality of Output Number 2
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xD

## 209Dh – Position Level 1 for Digital Output Definition

### Object Description

<b>Index</b>	209D
<b>Description</b>	The value of this object is used by the Digital Outputs Functionality object (Object 209Ch) as the first position value for a condition that controls a digital output.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	user-defined position
<b>Lower Limit</b>	0x80000001
<b>Upper Limit</b>	0x7FFFFFFF

## 209Eh – Position Level 2 for Digital Output Definition

### Object Description

<b>Index</b>	209E
<b>Description</b>	The value of this object is used by the Digital Outputs Functionality object (Object 209Ch) as the second position value for a condition that controls a digital output.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No

<b>Default Value</b>	0x0
<b>Unit</b>	user-defined position
<b>Lower Limit</b>	0x80000001
<b>Upper Limit</b>	0x7FFFFFFF

## 209Fh – Velocity Level 1 for Digital Output Definition

### Object Description

<b>Index</b>	209F
<b>Description</b>	The value of this object is used by the Digital Outputs Functionality object (Object 209Ch) as the first velocity value for a condition that controls a digital output.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	user-defined velocity
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

## 20A0h – Velocity Level 2 for Digital Output Definition

### Object Description

<b>Index</b>	20A0
<b>Description</b>	The value of this object is used by the Digital Outputs Functionality object (Object 209Ch) as the second velocity value for a condition that controls a digital output.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	user-defined velocity
<b>Lower Limit</b>	0x80000001
<b>Upper Limit</b>	0x7FFFFFFF



## 20A1h – Over-Voltage Threshold

### Object Description

<b>Index</b>	20A1
<b>Description</b>	This object indicates the level for detection of the bus over-voltage condition.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xCB20
<b>Unit</b>	millivolt
<b>Lower Limit</b>	0x2CEC
<b>Upper Limit</b>	0xCB20

## 20ACh – Software Position Limit Mode

### Object Description

<b>Index</b>	20AC
<b>Description</b>	<p>This object enables/disables software position limits. It enables/disables the absolute position limits for the position demand value and the position actual value. Every new target position is checked against these limits.</p> <p>0 = Limits disabled  1 = Limits enabled  2 = Limits enabled with Stop position functionality</p>
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x0002

## 20B5h – Position In Window

**Object Description**

<b>Index</b>	20B5
<b>Description</b>	This object indicates the "in position" flag. The in position window is set in object 6067h
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

**20BAh – Remote Hardware Enable Status****Object Description**

<b>Index</b>	20BA
<b>Description</b>	This object indicates the state of the Remote enable input, which is digital input mode number 5 in object 20E0h (Digital Input Mode). 0 = Remote enable input off 1 = Remote enable input on
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x0001

**20CCh – Run Time****Object Description**

<b>Index</b>	20CC
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<b>Description</b>	This object indicates the total elapsed run time of the drive since production. The value of this object cannot be reset.
<b>Object Code</b>	Variable
<b>Data Type</b>	Visible_String

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0
<b>Lower Limit</b>	0
<b>Upper Limit</b>	0

**20CFh – Under-Voltage Threshold****Object Description**

<b>Index</b>	20CF
<b>Description</b>	This object indicates the level for detection of an under-voltage condition.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x3138
<b>Unit</b>	millivolt
<b>Lower Limit</b>	0x3138
<b>Upper Limit</b>	0xCB20

**20D9h – Velocity Loop Input Filter****Object Description**

<b>Index</b>	20D9
<b>Description</b>	This object indicates the low pass filter cutoff frequency for the velocity loop.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

**Entry Description**

<b>Access</b>	Read/Write
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<b>PDO Mapping</b>	No
<b>Default Value</b>	0x64
<b>Unit</b>	Hz
<b>Lower Limit</b>	0x1
<b>Upper Limit</b>	0x7530

## 20DEh – Load Encoder Resolution

### Object Description

<b>Index</b>	20DE
<b>Description</b>	This object indicates the configured encoder increments and number of load revolutions. It is calculated by the following formula: position encoder resolution = (encoder increments/motor revolutions)
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x2
<b>Lower Limit</b>	0x2
<b>Upper Limit</b>	0x2

  

<b>Sub-Index</b>	001
<b>Description</b>	Encoder Increments
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x1
<b>Unit</b>	counts
<b>Lower Limit</b>	0x1
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Load Revolutions
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x1
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x1
<b>Upper Limit</b>	0xFFFFFFFF

## 20E0h – Digital Input Mode

### Object Description

<b>Index</b>	20E0
<b>Description</b>	<p>This object defines the function of each digital input.</p> <p>0 = Disabled</p> <p>1 = General</p> <p>2 = Homing</p> <p>3 = Limit switch clockwise</p> <p>4 = Limit switch counterclockwise</p> <p>5 = Remote enable</p> <p>6 = Start motion command for profiled position operation mode.</p> <p>7 = Touch probe 1</p> <p>8 = Touch probe 2</p> <p>9 = Motion select 0</p> <p>10 = Motion select 1</p> <p>11 = Motion select 2</p> <p>12 = Motion select 3</p> <p>13 = Motion Start</p> <p>14 = Motion Stop</p>
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned16

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x4
<b>Lower Limit</b>	0x0

<b>Upper Limit</b>	0x4
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<b>Sub-Index</b>	001
<b>Description</b>	Functionality of Input Number 1
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xE

  

<b>Sub-Index</b>	002
<b>Description</b>	Functionality of Input Number 2
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xE

  

<b>Sub-Index</b>	003
<b>Description</b>	Functionality of Input Number 3
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xE

<b>Sub-Index</b>	004
<b>Description</b>	Functionality of Input Number 4
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xE

## 20E6h – Record Done Indicator

### Object Description

<b>Index</b>	20E6
<b>Description</b>	This object indicates whether the recording is complete and data is available. 0 = Record in progress 1 = Record done
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x1
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x1

## 20EEh – Velocity Limit

### Object Description

<b>Index</b>	20EE
<b>Description</b>	This object indicates the maximum velocity for a drive and motor.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xF4240

<b>Unit</b>	RPM/100
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

## 20F1h – Motor Encoder Resolution

### Object Description

<b>Index</b>	20F1
<b>Description</b>	This object indicates the resolution of the motor encoder in number of lines per revolution of the motor.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x1000
<b>Unit</b>	counts per revolution
<b>Lower Limit</b>	0x1000
<b>Upper Limit</b>	0x1000

## 20F2h – Analog Input

### Object Description

<b>Index</b>	20F2
<b>Description</b>	This object returns the value of the analog input.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0000
<b>Unit</b>	millivolt
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

## 20F4h – Analog Input Current Scaling

### Object Description



<b>Index</b>	20F4
<b>Description</b>	This object indicates the scaling value of the analog current command from analog input.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	ampere/volt
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

**20F6h – Analog Input Offset****Object Description**

<b>Index</b>	20F6
<b>Description</b>	<p>This object indicates a value that is added to the analog input to the drive, to compensate for offset in the analog input signal.</p> <p>The analog input offset can be automatically set to the current analog input value by calling the analog zero function (object 2462h).</p>
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x30AA
<b>Unit</b>	millivolt
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

**20F7h – Analog Input Velocity Scaling****Object Description**

<b>Index</b>	20F7
<b>Description</b>	This object indicates the scaling value of the analog velocity command from the analog input.

<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	RPM/100/millivolt
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

**20F8h – Analog Input Zero****Object Description**

<b>Index</b>	20F8
<b>Description</b>	<p>This object sets the value of the analog input offset (object 20F6h) so that the current analog input value reading will return zero. The offset value is calculated from an average of 64 samples of the drive analog input.</p> <p>To perform the zeroing, the object must be written with the value of the analog input number; for example, write 1 to the object to zero analog input 1.</p>
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x0001

**2116h – Point to Point Generator Status****Object Description**

<b>Index</b>	2116
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<b>Description</b>	This object indicates the state of the point to point trajectory generator. 0 = Acceleration or constant speed 1 = Deceleration 2 = Finished 3 = Idle
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0000
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

**2614h – PDO Address Tx****Object Description**

<b>Index</b>	2614
<b>Description</b>	This object can be used to monitor memory for production and testing purposes
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

**2615h – PDO Data Tx****Object Description**

<b>Index</b>	2615
<b>Description</b>	This object can be used to monitor memory for production and testing purposes
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

## 2616h – PDO Address Rx

### Object Description

<b>Index</b>	2616
<b>Description</b>	This object can be used to monitor memory for production and testing purposes.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 2617h – PDO Data Rx

### Object Description

<b>Index</b>	2617
<b>Description</b>	This object can be used to monitor memory for production and testing purposes.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

## 2618h – Sync Counter Out

### Object Description

<b>Index</b>	2618
<b>Description</b>	This object indicates the PLL error in synchronous operation.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

**2619h – PFB Sync Delay****Object Description**

<b>Index</b>	2619
<b>Description</b>	This object indicates the delay for sending the PFB in synchronous operation.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

**261Ah – PCMD Sync Delay****Object Description**

<b>Index</b>	261A
<b>Description</b>	This object indicates the delay for reading the PCMD in synchronous operation.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No

<b>Default Value</b>	0x0000
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

## 261Bh – PLL State

### Object Description

<b>Index</b>	261B
<b>Description</b>	PLL state in synchronous operation. 0 = Unlocked 1 = Locking 2 = Locked 3 = Lost
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFF

## 2626h – Sync Lost Counter

### Object Description

<b>Index</b>	2626
<b>Description</b>	This object indicates the number of lost sync messages in synchronized operation.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFF

## 2627h – RPDO Lost Counter

**Object Description**

<b>Index</b>	2627
<b>Description</b>	This object indicates the number of lost PDO messages in synchronized operation.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFF

**2628h – Position Derivative for Missing RPDO****Object Description**

<b>Index</b>	2628
<b>Description</b>	This object indicates the change in position at the last received synced PDO, which can be used in the event of a lost PDO.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

**2629h – Custom TBPRD****Object Description**

<b>Index</b>	2629
<b>Description</b>	This object indicates the time base of the drive real-time interrupt.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0000
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

## 262Ah – Sync RT Counter

### Object Description

<b>Index</b>	262A
<b>Description</b>	This object indicates the number of real-time interrupts between two sync messages
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 262Bh – Allowed Lost Syncs

### Object Description

<b>Index</b>	262B
<b>Description</b>	This object indicates the maximum number of lost sync messages before a PLL lost fault is generated.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x000F
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x7FFF

## 262Ch – Sync Allowed Window

### Object Description



<b>Index</b>	262C
<b>Description</b>	This object indicates the maximum deviation of a sync message before a PLL lost fault is generated.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x30D4
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

**262Dh – High Resolution Timer Difference****Object Description**

<b>Index</b>	262D
<b>Description</b>	This object indicates the difference between the internal timer and the received value.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

**2F01h – Calibration Data Status****Object Description**

<b>Index</b>	2F01
<b>Description</b>	This object indicates the state of the calibration data: 0 = Calibration saved -2 = No calibration saved
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read/Write
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<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Lower Limit</b>	0xFFFE
<b>Upper Limit</b>	0x0001

## 2F05h – Drive Enabled Time

### Object Description

<b>Index</b>	2F05
<b>Description</b>	This object indicates the accumulative time of the drive in Enabled state.
<b>Object Code</b>	Variable
<b>Data Type</b>	Visible_String

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	-
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

## 2F06h – Phase A PWM

### Object Description

<b>Index</b>	2F06
<b>Description</b>	This object indicates the value of Phase A PWM.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

## 2F07h – Phase B PWM

### Object Description

<b>Index</b>	2F07
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<b>Description</b>	This object indicates the value of Phase B PWM.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

**2F08h – Maximum Velocity Error****Object Description**

<b>Index</b>	2F08
<b>Description</b>	This object indicates the maximum value for the velocity error. Writing a value of 0 disables velocity error monitoring.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	RPM/100
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

**2F09h – Velocity Loop Out****Object Description**

<b>Index</b>	2F09
<b>Description</b>	This object indicates the value of the velocity loop output (control effort). This value is the input of the current loop in all operation modes except Torque mode (operation mode 4).
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Unit</b>	milliampere
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

## 2F0Ah – Velocity Over-Speed

### Object Description

<b>Index</b>	2F0A
<b>Description</b>	This object indicates the velocity value that triggers the over-speed protection fault.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x1E8480
<b>Unit</b>	RPM/100
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

## 2F0Bh – Maximum Position Derivative

### Object Description

<b>Index</b>	2F0B
<b>Description</b>	This object indicates the value of the maximum position derivative for the position command that is received from the CANopen master in Interpolated Position mode (operation mode 7). Writing a value of 0 disables this functionality.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	counts

<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

## 2F0Ch – Parameter Help String1

### Object Description

<b>Index</b>	2F0C
<b>Description</b>	Returns the help string for a command (a CANopen object). The help string is divided into 2 strings, which are located in objects 2F0Ch (first string) and 2F0Dh (second string). The command's CANopen index is written to object 2F0Eh and the help string is read in objects 2F0Ch and 2F0Dh.
<b>Object Code</b>	Variable
<b>Data Type</b>	Visible_String

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

## 2F0Dh – Parameter Help String2

### Object Description

<b>Index</b>	2F0D
<b>Description</b>	Returns the help string for a command (a CANopen object). The help string is divided into 2 strings, which are located in objects 2F0Ch (first string) and 2F0Dh (second string). The command's CANopen index is written to object 2F0Eh and the help string is read in objects 2F0Ch and 2F0Dh.
<b>Object Code</b>	Variable
<b>Data Type</b>	Visible_String

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No

<b>Default Value</b>	-
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

## 2F0Eh – Parameter Help Index

### Object Description

<b>Index</b>	2F0E
<b>Description</b>	<p>This object indicates the CANopen index of the command for which a help string is requested.</p> <p>The help string is divided into 2 strings, which are located in objects 2F0Ch (first string) and 2F0Dh (second string).</p> <p>The command's CANopen index is written to object 2F0Eh and the help string is read in objects 2F0Ch and 2F0Dh.</p>
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 2F0Fh – Parameter Index List

### Object Description

<b>Index</b>	2F0F
<b>Description</b>	<p>Lists the indexes of all the parameters that are saved in the non-volatile memory (EEPROM).</p> <p>Writing 0 to sub-index 1 starts enumeration.</p> <p>Reading sub-index 2 retrieves the CANopen index of the EEPROM parameter. Upon each read the enumerator automatically advances. Enumeration ends when reading 0xFFFFFFFF.</p>
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x2
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF
<b>Sub-Index</b>	001
<b>Description</b>	<b>Parameter In List Index</b>
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Parameter In List
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 2F10h – Recorder Channels

### Object Description

<b>Index</b>	2F10
<b>Description</b>	<p>This object selects the recorded data (sub-index 1 is Number of Records, sub-index 2 is the CANopen index of the first channel, sub-index 3 is the CANopen index of the second channel, etc.).</p> <p>Up to 4 channels are available for recording simultaneously. The total length of the recording depends on the number of channels selected.</p>
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x5
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF



<b>Sub-Index</b>	001
<b>Description</b>	Number of Records
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x4

  

<b>Sub-Index</b>	002
<b>Description</b>	Channel1 Index
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

  

<b>Sub-Index</b>	003
<b>Description</b>	Channel2 Index
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

  

<b>Sub-Index</b>	004
<b>Description</b>	Channel3 Index
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	005
<b>Description</b>	Channel4 Index
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 2F11h – Recorder Sample Cycle

### Object Description

<b>Index</b>	2F11
<b>Description</b>	This object is multiplied by 62.5 microseconds to produce the recording sample period. For every 62.5 microseconds sample cycle, the recorder adds a new sample to its recording buffer.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x7FFF

## 2F12h – Recorder Trigger

### Object Description

<b>Index</b>	2F12
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<b>Description</b>	<p>This object indicates the trigger for the recording process.</p> <p>Sub-index 1 determines whether the recording will start immediately or after a condition is fulfilled .The remaining sub-indexes are used for conditional recording.</p> <p>0 = Immediate recording  1 = Conditional recording  2 = Recording initiated by fault</p> <p>Sub-index 2 indicates the CANopen index for the channel.</p> <p>Sub-index 3 indicates the value of the condition.</p> <p>Sub-index 4 indicates the direction of the comparator (1 for rising edge, 0 for falling edge).</p> <p>Sub-index 5 indicates the location of the condition in the recording buffer.</p>
<b>Object Code</b>	Array
<b>Data Type</b>	Integer32

#### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x5
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

  

<b>Sub-Index</b>	001
<b>Description</b>	Recorder Trigger Condition
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x2

---

<b>Sub-Index</b>	002
<b>Description</b>	<b>Recorder Condition Channel Index</b>
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

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<b>Sub-Index</b>	003
<b>Description</b>	Recorder Condition Value
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

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<b>Sub-Index</b>	004
<b>Description</b>	Recorder Condition Comparator
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x1

---

<b>Sub-Index</b>	005
<b>Description</b>	Recorder Buffer Location
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7A120

## 2F13h – Recorder Total Number of Points

### Object Description

<b>Index</b>	2F13
<b>Description</b>	This object indicates the total number of points available for recording.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFF

## 2F14h – Recordable Parameters

### Object Description

<b>Index</b>	2F14
<b>Description</b>	<p>This object indicates the list of parameters available for recording.</p> <p>Writing 0 to sub-index 1 starts enumeration.</p> <p>Reading sub-index 2 retrieves the CANopen index of the recordable parameter. Upon each read the enumerator automatically advances. Enumeration ends when reading 0xFFFFFFFF.</p>
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Sub-Index</b>	000
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<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x2
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	001
<b>Description</b>	Recordable List Index
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	002
<b>Description</b>	Recordable Parameter
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 2F15h – Recorder Number of Points per Channel

### Object Description

<b>Index</b>	2F15
<b>Description</b>	The object indicates the number of points per channel to be recorded. This value multiplied by the number of recorded channels cannot exceed the total number of points (object 2F13h).
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0xFFFF

## 2F16h – Recorder Start

### Object Description

<b>Index</b>	2F16
<b>Description</b>	Writing 1 to this object starts recording. Writing 0 cancels recording if in progress.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned8

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0

<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x1

## 2F17h – Number of Recorded Points

### Object Description

<b>Index</b>	2F17
<b>Description</b>	This object indicates the number of recorded points for a channel.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 2F18h – Recorder Results

### Object Description

<b>Index</b>	2F18
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<b>Description</b>	<p>This object holds the results of the recording.          Setting sub-index 1 to zero starts enumeration.          Reading sub-index 2 retrieves the recorded point.          Upon each read the next point is retrieved.          Reading is repeated according to the value of object 2F15h (Recorder Number of Points per Channel).          If more than a single channel was recorded, the recorded points are arranged as follows:          1st channel 1st point          2nd channel 1st point          3rd channel 1st point          1st channel 2nd point          2nd channel 2nd point          3rd channel 2nd point          .          .          .          1st channel last point          2nd channel last point          3rd channel last point</p>
<b>Object Code</b>	Array
<b>Data Type</b>	Integer32

#### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x3
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF
<b>Sub-Index</b>	001
<b>Description</b>	Reset Results Index
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x1

<b>Sub-Index</b>	002
<b>Description</b>	Recorder Channel Result
<b>Data Type</b>	Integer32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	003
<b>Description</b>	Result Index
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 2F19h – Phase Advance Factor

### Object Description

<b>Index</b>	2F19
<b>Description</b>	This object indicates the factor of the phase advance as a function of velocity.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xBB8
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

## 2F1Ah – Phase Advance Limit

### Object Description

<b>Index</b>	2F1A
<b>Description</b>	This object indicates the limit of the phase advance in degrees.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x46
<b>Unit</b>	Deg

<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x5A

## 2F1Bh – Drive Address

### Object Description

<b>Index</b>	2F1B
<b>Description</b>	This object indicates the address of the drive in the CANopen network. To apply a change in the address, save the new address to EEPROM (Store Parameter Field process object 1010h) and reset the drive.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0065
<b>Unit</b>	Deg
<b>Lower Limit</b>	0x0001
<b>Upper Limit</b>	0x007F

## 2F1Ch – PLL Factor

### Object Description

<b>Index</b>	2F1C
<b>Description</b>	This object indicates the factor for CANopen synchronized operation PLL.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x10000
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

## 2F1Dh – Field Weakening Factor

**Object Description**

<b>Index</b>	2F1D
<b>Description</b>	This object indicates the field weakening as a function of velocity.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xC8
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

**2F1Eh – Field Weakening Limit****Object Description**

<b>Index</b>	2F1E
<b>Description</b>	This object indicates the field weakening current limit in mA.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x2BC
<b>Unit</b>	milliampere
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x2EE0

**2F1Fh – CAN Open Baudrate**

This object indicates the baudrate of the drive in the CANopen network.

To apply a change in the baudrate, save the new baudrate to EEPROM (Store Parameter Field process object 1010h) and reset the drive.

**Object Description**

<b>Index</b>	2F1F
<b>Description</b>	0 = 1 Mbit/s 1 = Reserved 2 = 500 Kbit/s 3 = 250 Kbit/s 4 = 125 Kbit/s 5 = Reserved 6 = 50 Kbit/s 7 = 20 Kbit/s 8 = 10 Kbit/s
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x0008

**2F20h – Phase Advance Start Velocity****Object Description**

<b>Index</b>	2F20
<b>Description</b>	This object indicates the phase advance start velocity.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

**2F21h – Save Process Active****Object Description**

<b>Index</b>	2F21
<b>Description</b>	This object indicates whether the Store Parameter Field process (object 1010h) is running. 0 = Store Parameter Field process is not active 1 = Store Parameter Field process is active
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x0001

**2F22h – Home On Edge Current Saturation****Object Description**

<b>Index</b>	2F22
<b>Description</b>	This object indicates the current saturation for homing on edge method (home methods -1, -2, -3, -4).
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x07D0
<b>Unit</b>	mA
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x2EE0

**2F23h – Home On Edge Time****Object Description**

<b>Index</b>	2F23
<b>Description</b>	This object indicates the minimum time to wait in stall position before setting home, for homing on edge method (home methods -1, -2, -3, -4).
<b>Object Code</b>	Variable

<b>Data Type</b>	Integer16
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**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x07D0
<b>Unit</b>	millisecond
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x2EE0

**2F24h – Reserved1****Object Description**

<b>Index</b>	2F24
<b>Description</b>	Reserved1
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x07D0
<b>Unit</b>	millisecond
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x2EE0

**2F25h – Reserved2****Object Description**

<b>Index</b>	2F25
<b>Description</b>	Reserved2
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x07D0
<b>Unit</b>	millisecond



<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x2EE0

## 2F26h – Reserved3

### Object Description

<b>Index</b>	2F26
<b>Description</b>	Reserved3
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x07D0
<b>Unit</b>	millisecond
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x2EE0

## 2F27h – Reserved4

### Object Description

<b>Index</b>	2F27
<b>Description</b>	Reserved4
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x07D0
<b>Unit</b>	millisecond
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x2EE0

## 2F28h – Home End Position Offset

### Object Description

<b>Index</b>	2F28
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<b>Description</b>	This object indicates the difference between the zero position for the application and the machine home position. After the machine home position is found and homing is completed, the zero position is offset from the home position by adding the home offset value to the home position. All subsequent absolute moves are executed relative to this new zero position. If this object is not implemented, home offset is considered to be 0. Negative values indicate the opposite direction.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	user-defined position
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

**2F29h – Current High Limit****Object Description**

<b>Index</b>	2F29
<b>Description</b>	This object indicates the maximum current for generating torque in the motor.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x2EE0
<b>Unit</b>	mA
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

**2F2Ah – Current Low Limit****Object Description**

<b>Index</b>	2F2A
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<b>Description</b>	This object indicates the minimum current for generating torque in the motor.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0xD120
<b>Unit</b>	mA
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

**2F30h – CAN Buffer Overflow Counter****Object Description**

<b>Index</b>	2F30
<b>Description</b>	CAN buffer overflow counter.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

**2F70h – LED Color Select****Object Description**

<b>Index</b>	2F70
<b>Description</b>	Selects standby LED configuration 0 = Blinking green 1 = Constant yellow
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read/Write
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<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x0001

## 2F76h – Reset to Bootloader

### Object Description

<b>Index</b>	2F76
<b>Description</b>	This object initiates reset to boot loader. The drive is reset to bootloader when 0x00747372 (ASCII value of "rst") is written.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 2F77h – Stop Position

### Object Description

<b>Index</b>	2F77
<b>Description</b>	If object 0x20AC (Software Position Limit Mode) is set to 2, drive will stop on crossing of stop position value.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	counts
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 2F78h – Motor Ke

### Object Description

<b>Index</b>	2F78
<b>Description</b>	This object indicates the BEMF/velocity ratio of the motor. (KE)
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0
<b>Unit</b>	Volts/Radians/sec (= Kt in [A/Nm])
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	10000

## 2F7Ah – Serial Number

### Object Description

<b>Index</b>	2F7A
<b>Description</b>	This object contains the serial number of the device, including non-integer characters.
<b>Object Code</b>	Variable
<b>Data Type</b>	Visible_String

### Entry Description

<b>Access</b>	Constant
<b>PDO Mapping</b>	No
<b>Default Value</b>	SN:000000-000000
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

## 2F7Bh – Boot Version

### Object Description

<b>Index</b>	2F7B
<b>Description</b>	This object contains the version number of the boot software
<b>Object Code</b>	Variable
<b>Data Type</b>	Visible_String

**Entry Description**

<b>Access</b>	Constant
<b>PDO Mapping</b>	No
<b>Default Value</b>	No version
<b>Lower Limit</b>	-
<b>Upper Limit</b>	-

**2F7Ch – Motor Info****Object Description**

<b>Index</b>	2F7C
<b>Description</b>	This object contains pre-programmed motor parameters and info.
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned32

**Entry Description**

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x18
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF
<b>Sub-Index</b>	001
<b>Description</b>	'M'
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	'O'
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x4F
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	003
<b>Description</b>	'T'
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x54
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	004
<b>Description</b>	'O'
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

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<b>Sub-Index</b>	005
<b>Description</b>	'R'
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

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<b>Sub-Index</b>	006
<b>Description</b>	Current Integral Gain
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

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<b>Sub-Index</b>	007
<b>Description</b>	Current Proportional Gain
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---



<b>Sub-Index</b>	008
<b>Description</b>	Motor Pitch
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	009
<b>Description</b>	Motor Poles
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	010
<b>Description</b>	Phase Advance Factor
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	011
<b>Description</b>	Phase Advance Limit
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	degree
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	012
<b>Description</b>	Field Weakening Factor
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	013
<b>Description</b>	Field Weakening Limit
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	milliampere
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	014
<b>Description</b>	Motor Ke
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0
<b>Unit</b>	volt/RPM
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	015
<b>Description</b>	Peak Current
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	milliampere
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	016
<b>Description</b>	Peak Current Limit
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	milliampere
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	017
<b>Description</b>	Max Current
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	milliampere
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	018
<b>Description</b>	Max Current Limit
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	milliampere
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

---

<b>Sub-Index</b>	019
<b>Description</b>	Motor Rated Current
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	milliampere
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

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<b>Sub-Index</b>	020
<b>Description</b>	I2T Fault Threshold
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	021
<b>Description</b>	Motor Model
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	022
<b>Description</b>	HW revision
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	023
<b>Description</b>	Motor Size
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	024
<b>Description</b>	Password for protected values
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 2F7Dh – Serial Number For CAN ID

### Object Description

<b>Index</b>	2F7D
<b>Description</b>	This object indicates the serial number to be configured.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

## 2F7Eh – New CAN ID

### Object Description

<b>Index</b>	2F7E
<b>Description</b>	This object indicates the new CAN ID to be configured for a specific serial number in 0x2F7D.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned8

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	101
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x00

<b>Upper Limit</b>	0xFF
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## 2F7Fh – CAN ID Configuration

### Object Description

<b>Index</b>	2F7F
<b>Description</b>	This object completes the CAN ID configuration process 0. Update CAN Node ID 1. Save in EEPROM
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned8

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x00
<b>Upper Limit</b>	0xFF

## 2F80h – User Parameters

### Object Description

<b>Index</b>	2F80
<b>Description</b>	Parameters that can be programmed by user. These parameters are stored in drive EEPROM by the store parameters command.
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x5
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF



<b>Sub-Index</b>	001
<b>Description</b>	Parameter 0
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Parameter 1
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	003
<b>Description</b>	Parameter 2
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	004
<b>Description</b>	Parameter 3
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x00000000
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	005
<b>Description</b>	Parameter 4
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 2F81h – Savable Parameters

### Object Description

<b>Index</b>	2F81
<b>Description</b>	<p>This object indicates the list of parameters available for saving.</p> <p>Setting sub-index 1 to zero starts enumeration.</p> <p>Reading sub-index 2 retrieves the CANopen index of the recordable parameter. For each read the enumerator automatically advances. Enumeration ends when 0xFFFFFFFF is read.</p>
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x2
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	001
<b>Description</b>	<b>Recordable List Index</b>
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Recordable Parameter
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 2F82h – PLL Lock

### Object Description

<b>Index</b>	2F82
<b>Description</b>	<p>This object controls the synchronization method of the drives PLL.</p> <p>0 = PLL is not synchronized</p> <p>1 = PLL is synchronized with CANopen sync message - this mode creates a fault at Sync Lost in operation mode 8.</p> <p>2 = PLL is synchronized with the high resolution time stamp (object 1013h)</p> <p>3 = PLL is synchronized with CANopen sync message - this mode creates a fault at Sync Lost in any operation mode.</p>
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0001
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x0003

## 2F83h – Motion Time

### Object Description

<b>Index</b>	2F83
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<b>Description</b>	Allows motion to start at a specific time in profile position operation mode (1). The time is based on object 1013h (High Resolution Time Stamp). To start motion at a specific time: - Set bit 11 in Controlword (object 6040h) to 1 to enable starting motion at a given time - Set object 2F82h (PLL Lock) to 2 (optional) - Set start time in object 2F83h. - The motion will start according to the time specified.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x1
<b>Unit</b>	microsecond
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

**2F84h – Backlash Compensation Distance****Object Description**

<b>Index</b>	2F84
<b>Description</b>	Sets the backlash compensation distance. Applicable in profile position operation mode (1).
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	counts
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

**2F85h – Voltage Level for Digital Output Definition****Object Description**

<b>Index</b>	2F85
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<b>Description</b>	The value of this object is used by the over-voltage functionality of object 209Ch (Digital Output Functionality). As the voltage rises above the set value it will set the digital output. This voltage has a hysteresis of +/- 500 millivolt.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xCB20
<b>Unit</b>	user-defined position
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xCB20

**2F86h – Save Pfb On Power Off****Object Description**

<b>Index</b>	2F86
<b>Description</b>	This object indicates whether the actual position value (object 6063h) is saved in EEPROM at power off of the bus voltage supply, and restored at the next power on. This feature is not active at shutdown of the auxiliary power supply. 1 = Save enabled 0 = Save disabled
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x7FFF

**2F87h – Manufacture Specific Bits Mode****Object Description**

<b>Index</b>	2F87
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<b>Description</b>	This object defines the function of each manufacturer specific bit in the controlword (bits 11-15). 0 = Disabled 1 = In profile position mode, the profile velocity will be reduced by 50% 2 = Begin on time select bit for profile position mode
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned16

#### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x5
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x5

<b>Sub-Index</b>	001
<b>Description</b>	Functionality of controlword bit 11
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x2
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x2

<b>Sub-Index</b>	002
<b>Description</b>	Functionality of controlword bit 12
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x2



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<b>Sub-Index</b>	003
<b>Description</b>	Functionality of controlword bit 13
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x2

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<b>Sub-Index</b>	004
<b>Description</b>	Functionality of controlword bit 14
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x2

<b>Sub-Index</b>	005
<b>Description</b>	Functionality of controlword bit 15
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x2

## 2F88h – Backlash Compensation Mode

### Object Description

<b>Index</b>	2F88
<b>Description</b>	<p>The drive has two types of backlash compensation.</p> <p>Type 1. Prior to starting the first movement after enable, and upon every direction change, the backlash compensation distance is added to the target position. Upon the first movement after enable, the drive will first move the backlash compensation distance in the opposite direction of the move command, and then it will execute the move command.</p> <p>Type 2. At the end of every movement in the direction of the backlash, the backlash compensation distance is added to the target position.</p>
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Unit</b>	counts
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x0001

## 2F89h – Position Backup Restore Window

### Object Description

<b>Index</b>	2F89
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<b>Description</b>	Sets position restore verification window. Applicable only when object 0x2F86 =1. On bootup, the restored encoder position and actual encoder position are compared. If the difference is within the window, the Position Backup Restore Status (object 0x2F8A) is set to 1.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	counts
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

**2F8Ah – Position Backup Restore Status****Object Description**

<b>Index</b>	2F8A
<b>Description</b>	0 = Position was not restored correctly 1 = Position was restored correctly
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Unit</b>	counts
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x0001

**2F8Bh – Reduced Control Loop Frequency****Object Description**

<b>Index</b>	2F8B
<b>Description</b>	0 = Normal operation (Velocity loop 8 kHz, Position Loop 16 kHz) 1 = Reduced frequency (Velocity loop 16 kHz, Position Loop 32 kHz)

<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x0001

**2F90h – Path Segment 0**

Motion path

**Object Description**

<b>Index</b>	2F90
<b>Description</b>	Path Segment 0
<b>Object Code</b>	Array
<b>Data Type</b>	Integer32

**Entry Description**

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x8
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	001
<b>Description</b>	Target Position
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Cruise Velocity
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	003
<b>Description</b>	Acceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	004
<b>Description</b>	Deceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	005
<b>Description</b>	Controlword
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

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<b>Sub-Index</b>	006
<b>Description</b>	Delay
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

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<b>Sub-Index</b>	007
<b>Description</b>	Number of Iterations
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

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<b>Sub-Index</b>	008
<b>Description</b>	Next Segment Index
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 2F91h – Path Segment 1

### Object Description

<b>Index</b>	2F91
<b>Description</b>	Path Segment 1
<b>Object Code</b>	Array
<b>Data Type</b>	Integer32

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x8
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	001
<b>Description</b>	Target Position
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Cruise Velocity
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	003
<b>Description</b>	Acceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	004
<b>Description</b>	Deceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	005
<b>Description</b>	Controlword
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF



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<b>Sub-Index</b>	006
<b>Description</b>	Delay
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	007
<b>Description</b>	Number of Iterations
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	008
<b>Description</b>	Next Segment Index
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 2F92h – Path Segment 2

### Object Description

<b>Index</b>	2F92
<b>Description</b>	Path Segment 2
<b>Object Code</b>	Array
<b>Data Type</b>	Integer32

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x8
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	001
<b>Description</b>	Target Position
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Cruise Velocity
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	003
<b>Description</b>	Acceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	004
<b>Description</b>	Deceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	005
<b>Description</b>	Controlword
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	006
<b>Description</b>	Delay
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	007
<b>Description</b>	Number of Iterations
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	008
<b>Description</b>	Next Segment Index
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 2F93h – Path Segment 3

### Object Description

<b>Index</b>	2F93
<b>Description</b>	Path Segment 3
<b>Object Code</b>	Array
<b>Data Type</b>	Integer32

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x8
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	001
<b>Description</b>	Target Position
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Cruise Velocity
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	003
<b>Description</b>	Acceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	004
<b>Description</b>	Deceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	005
<b>Description</b>	Controlword
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	006
<b>Description</b>	Delay
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	007
<b>Description</b>	Number of Iterations
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	008
<b>Description</b>	Next Segment Index
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 2F94h – Path Segment 4

### Object Description

<b>Index</b>	2F94
<b>Description</b>	Path Segment 4
<b>Object Code</b>	Array
<b>Data Type</b>	Integer32

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x8
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	001
<b>Description</b>	Target Position
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF



<b>Sub-Index</b>	002
<b>Description</b>	Cruise Velocity
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	003
<b>Description</b>	Acceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	004
<b>Description</b>	Deceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	005
<b>Description</b>	Controlword
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	006
<b>Description</b>	Delay
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	007
<b>Description</b>	Number of Iterations
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	008
<b>Description</b>	Next Segment Index
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 2F95h – Path Segment 5

### Object Description

<b>Index</b>	2F95
<b>Description</b>	Path Segment 5
<b>Object Code</b>	Array
<b>Data Type</b>	Integer32

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x8
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	001
<b>Description</b>	Target Position
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Cruise Velocity
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	003
<b>Description</b>	Acceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	004
<b>Description</b>	Deceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	005
<b>Description</b>	Controlword
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	006
<b>Description</b>	Delay
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	007
<b>Description</b>	Number of Iterations
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	008
<b>Description</b>	Next Segment Index
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 2F96h – Path Segment 6

### Object Description

<b>Index</b>	2F96
<b>Description</b>	Path Segment 6
<b>Object Code</b>	Array
<b>Data Type</b>	Integer32

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x8
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	001
<b>Description</b>	Target Position
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Cruise Velocity
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	003
<b>Description</b>	Acceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	004
<b>Description</b>	Deceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	005
<b>Description</b>	Controlword
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	006
<b>Description</b>	Delay
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	007
<b>Description</b>	Number of Iterations
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

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<b>Sub-Index</b>	008
<b>Description</b>	Next Segment Index
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 2F97h – Path Segment 7

### Object Description

<b>Index</b>	2F97
<b>Description</b>	Path Segment 7
<b>Object Code</b>	Array
<b>Data Type</b>	Integer32

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x8
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	001
<b>Description</b>	Target Position
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Cruise Velocity
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	003
<b>Description</b>	Acceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	004
<b>Description</b>	Deceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	005
<b>Description</b>	Controlword
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	006
<b>Description</b>	Delay
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	007
<b>Description</b>	Number of Iterations
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	008
<b>Description</b>	Next Segment Index
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 2F98h – Path Segment 8

### Object Description

<b>Index</b>	2F98
<b>Description</b>	Path Segment 8
<b>Object Code</b>	Array
<b>Data Type</b>	Integer32

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x8
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	001
<b>Description</b>	Target Position
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Cruise Velocity
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	003
<b>Description</b>	Acceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	004
<b>Description</b>	Deceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	005
<b>Description</b>	Controlword
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	006
<b>Description</b>	Delay
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	007
<b>Description</b>	Number of Iterations
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

---

<b>Sub-Index</b>	008
<b>Description</b>	Next Segment Index
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 2F99h – Path Segment 9

### Object Description

<b>Index</b>	2F99
<b>Description</b>	Path Segment 9
<b>Object Code</b>	Array
<b>Data Type</b>	Integer32

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x8
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	001
<b>Description</b>	Target Position
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Cruise Velocity
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	003
<b>Description</b>	Acceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	004
<b>Description</b>	Deceleration
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	005
<b>Description</b>	Controlword
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF



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<b>Sub-Index</b>	006
<b>Description</b>	Delay
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

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<b>Sub-Index</b>	007
<b>Description</b>	Number of Iterations
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

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<b>Sub-Index</b>	008
<b>Description</b>	Next Segment Index
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 2F9Ah – Path Segment Index

### Object Description

<b>Index</b>	2F9A
<b>Description</b>	Path Segment Index
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	Volts/Radians/sec (= Kt in [A/Nm])
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x10000

## 2FC0h – Calibration Table

### Object Description

<b>Index</b>	2FC0
<b>Description</b>	Calibration Table
<b>Object Code</b>	Variable
<b>Data Type</b>	DOMAIN

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	NULL
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x0

## 2FC1h – Calibration Sector Erase

### Object Description

<b>Index</b>	2FC1
<b>Description</b>	Set 0x6563616c to erase calibration sector
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 2FC2h – Data Sector

### Object Description

<b>Index</b>	2FC2
<b>Description</b>	Data Sector
<b>Object Code</b>	Variable
<b>Data Type</b>	DOMAIN

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	NULL
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x0

## 2FC3h – Data Sector Erase

### Object Description

<b>Index</b>	2FC3
<b>Description</b>	Set 0x65646174 to erase calibration sector
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read/Write
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<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 2FC4h – CAN Error Counter

### Object Description

<b>Index</b>	2FC4
<b>Description</b>	This object keeps count of communication errors. The value of the counter can be reset by writing 0 to appropriate sub-index.
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned16

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x7
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0xFFFF
<b>Sub-Index</b>	001
<b>Description</b>	CAN controller is error active
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0xFFFF

6 sub indices with same parameters follow.

<b>Sub-Index</b>	002
<b>Description</b>	CAN controller is busoff
<b>Sub-Index</b>	003
<b>Description</b>	CAN controller receive buffer hardware overrun
<b>Sub-Index</b>	004
<b>Description</b>	CAN controller is error passive
<b>Sub-Index</b>	005
<b>Description</b>	CAN transmit software buffer overflow
<b>Sub-Index</b>	006
<b>Description</b>	CAN receive software buffer overflow
<b>Sub-Index</b>	007
<b>Description</b>	CAN form error flag

## 2FC5h – Virtual Inputs

### Object Description

<b>Index</b>	2FC5
<b>Description</b>	<p>This object provides virtual inputs.</p> <p>This object is organized bit-wise. The bits have the following meaning:</p> <p>bit 0: negative limit switch</p> <p>bit 1: positive limit switch</p> <p>bit 2: home switch</p> <p>bit 3: reserved</p> <p>bit 16-31: manufacturer-specific</p> <p>The bit values have the following meaning:</p> <p>0 = Switch is off</p> <p>1 = Switch is on</p>
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 2FC6h – Virtual Input Mode

### Object Description

<b>Index</b>	2FC6
<b>Description</b>	<p>This object defines the function of each virtual input.</p> <p>0 = Disabled</p> <p>1 = General</p> <p>2 = Homing</p> <p>3 = Limit switch clockwise</p> <p>4 = Limit switch counterclockwise</p> <p>5 = Remote enable</p> <p>6 = Start motion command for profiled position operation mode.</p> <p>7 = Touch probe 1</p> <p>8 = Touch probe 2</p>
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned16

**Entry Description**

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x4
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x4

<b>Sub-Index</b>	001
<b>Description</b>	Functionality of Input Number 1
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x8

<b>Sub-Index</b>	002
<b>Description</b>	Functionality of Input Number 2
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x8

<b>Sub-Index</b>	003
<b>Description</b>	Functionality of Input Number 3
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x8

<b>Sub-Index</b>	004
<b>Description</b>	Functionality of Input Number 4
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x8

## 2FC7h – Virtual Input Setting

### Object Description

<b>Index</b>	2FC7
<b>Description</b>	This object defines the setting of each virtual input. 0 = Disabled 1 = Current saturated 2 = Current saturated low 3 = Current saturated high
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned16

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x4
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x4

<b>Sub-Index</b>	001
<b>Description</b>	Functionality of Input Number 1
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x3



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<b>Sub-Index</b>	002
<b>Description</b>	Functionality of Input Number 2
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x3

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<b>Sub-Index</b>	003
<b>Description</b>	Functionality of Input Number 3
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x3

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<b>Sub-Index</b>	004
<b>Description</b>	Functionality of Input Number 4
<b>Data Type</b>	Unsigned16
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x3

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## 2FC8h – Input Start Motion Mode

### Object Description

<b>Index</b>	2FC8
<b>Description</b>	<p>This object defines the functionality of Motion Select; that is, the combination of digital inputs that sets the motion segment/s to be executed.</p> <p>If the value of object 0x2FC8 is <b>1</b> (input starts motion), each digital input represents one motion path segment (0, 1, 2 or 3). If Motion Select 0 is set to 0, motion segment 0 is executed, if Motion Select 1 is set to 1, motion segment #1 is executed, and so on.</p> <p>If the value of object 0x2FC8 is <b>0</b> (binary value starts motion), the binary value of the combined Motion Select inputs represents one single motion path segment (0, 1, 2, 3, 4, 5, 6 or 7).</p>
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x1

## 4 Device Profile Segment

### 6007h – Abort Connection Option Code

#### Object Description

<b>Index</b>	6007
<b>Description</b>	<p>This object indicates the action to be performed when one of the following events occurs:</p> <ul style="list-style-type: none"><li>CAN bus off</li><li>Heartbeat lost</li><li>Node guarding lost</li><li>NMT stopped (stop remote node indication activated)</li><li>Reset communication (reset communication indication activated)</li><li>Reset application (reset node indication activated)</li></ul> <p>The following value definitions are valid:</p> <ul style="list-style-type: none"><li>0 = No action</li><li>1 = Fault signal</li><li>2 = Disable voltage command</li><li>3 = Quick Stop command</li><li>-x = Manufacturer-specific</li></ul>
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

#### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0001
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x0003

### 603Fh – Error Code

#### Object Description

<b>Index</b>	603F
<b>Description</b>	This object indicates the error code of the last error that occurred in the drive device.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFF

**6040h – Controlword****Object Description**

<b>Index</b>	6040
<b>Description</b>	<p>This object controls the CiA-402 FSA, CiA-402 modes and manufacturer-specific entities.</p> <p>This object is organized bit-wise. The bits have the following meaning:</p> <ul style="list-style-type: none"> <li>bit 0: switch on</li> <li>bit 1: enable voltage</li> <li>bit 2: quick stop</li> <li>bit 3: enable operation</li> <li>bit 4-6: mode-specific</li> <li>bit 7: fault reset</li> <li>bit 8: halt</li> <li>bit 9: mode-specific</li> <li>bit 10: reserved</li> <li>bit 11: begin on time</li> <li>bit 12-15: manufacturer-specific</li> </ul>
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFF

**6041h – Statusword****Object Description**

<b>Index</b>	6041
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<b>Description</b>	<p>This object indicates the current state of the FSA, the operation mode and manufacturer-specific entities. This object is organized bit-wise. The bits have the following meaning:</p> <ul style="list-style-type: none"> <li>bit 0: ready to switch on</li> <li>bit 1: switched on</li> <li>bit 2: operation enabled</li> <li>bit 3: fault</li> <li>bit 4: voltage enabled</li> <li>bit 5: quick stop</li> <li>bit 6: switch on disabled</li> <li>bit 7: warning</li> <li>bit 8: manufacturer-specific</li> <li>bit 9: remote</li> <li>bit 10: target reached</li> <li>bit 11: internal limit active</li> <li>bit 12-13: mode-specific</li> <li>bit 14-15: manufacturer-specific</li> </ul>
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

#### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0000
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0xFFFF

## 6060h – Modes of Operation

#### Object Description

<b>Index</b>	6060
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<b>Description</b>	<p>The object selects the operational mode. This object shows only the value of the requested operation mode. The actual operation mode of the PDS is reflected in the Modes of Operation Display object (6061h)</p> <p>The following value definitions are valid:</p> <p>0 = no mode change / no mode assigned</p> <p>1 = profile position mode</p> <p>2 = velocity mode</p> <p>3 = profile velocity mode</p> <p>4 = profile torque mode</p> <p>5 = reserved</p> <p>6 = homing mode</p> <p>7 = interpolated position mode</p> <p>8 = cyclic synchronous position mode</p> <p>9 = cyclic synchronous velocity mode</p> <p>10 = cyclic synchronous torque mode</p> <p>-x = manufacturer-specific</p>
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer8

#### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x04
<b>Lower Limit</b>	0xFA
<b>Upper Limit</b>	0x08

## 6061h – Modes of Operation Display

#### Object Description

<b>Index</b>	6061
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<b>Description</b>	This object indicates the actual operation mode. The following value definitions are valid: 0 = no mode change / no mode assigned 1 = profile position mode 2 = velocity mode 3 = profile velocity mode 4 = profile torque mode 5 = reserved 6 = homing mode 7 = interpolated position mode 8 = cyclic synchronous position mode 9 = cyclic synchronous velocity mode 10 = cyclic synchronous torque mode -x = manufacturer-specific
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer8

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x00
<b>Lower Limit</b>	0x80
<b>Upper Limit</b>	0x0A

**6062h – Position Demand Value****Object Description**

<b>Index</b>	6062
<b>Description</b>	This object indicates the demanded position value.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Unit</b>	user-defined position
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

**6063h – Position Actual Value**

**Object Description**

<b>Index</b>	6063
<b>Description</b>	This object indicates the actual value of the position measurement device.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Unit</b>	user-defined position
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

**6064h – Position Actual Internal Value****Object Description**

<b>Index</b>	6064
<b>Description</b>	This object indicates the actual value of the position measurement device.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Unit</b>	user-defined position
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

**6065h – Following Error Window****Object Description**

<b>Index</b>	6065
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<b>Description</b>	This object indicates the symmetrical range of tolerated position values relative to the target position. If the current position is out of range a following error occurs. This object indicates the range of tolerated position values symmetrically to the position demand value (object 6062h). If the following error actual value (object 60F4h) is out of the following error window, a following error occurs. A following error may occur when a drive is blocked, or an unreachable profile velocity occurs, or due to incorrect closed-loop coefficients. If the value of the following error window is FFFFFFFFh, following control is disabled.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x2710
<b>Unit</b>	user-defined position
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

**6067h – Position Window****Object Description**

<b>Index</b>	6067
<b>Description</b>	This object indicates the symmetrical range of accepted positions relative to the target position. If the actual value of the position encoder is within the position window, the target position is regarded as reached. If the value of the position window is FFFFFFFFh, position window control is disabled.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x64
<b>Unit</b>	user-defined position
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

## 606Bh – Velocity Demand Value

### Object Description

<b>Index</b>	606B
<b>Description</b>	This object indicates the output value of the trajectory generator.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Unit</b>	user-defined velocity
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 606Ch – Velocity Actual Value

### Object Description

<b>Index</b>	606C
<b>Description</b>	This object indicates the actual velocity value derived either from the velocity sensor or the position sensor.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Unit</b>	user-defined velocity
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 606Dh – Velocity Window

### Object Description

<b>Index</b>	606D
<b>Description</b>	This object indicates the velocity window.
<b>Object Code</b>	Variable

<b>Data Type</b>	Unsigned16
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**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	user-defined velocity
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFF

**606Fh – Velocity Threshold****Object Description**

<b>Index</b>	606F
<b>Description</b>	This object indicates the velocity threshold.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Unit</b>	user-defined velocity
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0xFFFF

**6070h – Velocity Threshold Time****Object Description**

<b>Index</b>	6070
<b>Description</b>	This object indicates the velocity threshold time.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	millisecond

<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFF

## 6071h – Target Torque

### Object Description

<b>Index</b>	6071
<b>Description</b>	This object indicates the input value for the torque controller in profile torque mode.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0000
<b>Unit</b>	mNm
<b>Lower Limit</b>	0x8AD0
<b>Upper Limit</b>	0x7530

## 6073h – Max Current

### Object Description

<b>Index</b>	6073
<b>Description</b>	This object indicates the maximum permissible torque creating current in the motor.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x1194
<b>Unit</b>	mA
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x2EE0

## 6074h – Torque Demand Value

### Object Description

<b>Index</b>	6074
<b>Description</b>	This object provides the command value for the current loop.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0000
<b>Unit</b>	mA
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

**6075h – Motor Rated Current****Object Description**

<b>Index</b>	6075
<b>Description</b>	This object provides the motor rated current.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xBB8
<b>Unit</b>	mA
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

**6078h – Current Actual Value****Object Description**

<b>Index</b>	6078
<b>Description</b>	This object indicates the actual value of the current. It corresponds to the current in the motor.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0000
<b>Unit</b>	mA
<b>Lower Limit</b>	0x8000
<b>Upper Limit</b>	0x7FFF

## 6079h – DC Link Circuit Voltage

### Object Description

<b>Index</b>	6079
<b>Description</b>	This object indicates the instantaneous DC link current voltage at the drive device.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	mV
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 607Ah – Target Position

### Object Description

<b>Index</b>	607A
<b>Description</b>	This object indicates the commanded position to which the drive will move in position profile mode or cyclic synchronous position mode. The value of this object can be interpreted as absolute or relative depending on bit 6 of the controlword.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Unit</b>	user-defined position

<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 607Bh – Position Range Limit

### Object Description

<b>Index</b>	607B
<b>Description</b>	This object indicates the maximum and minimum position range limits. It limits the numerical range of the input value. Upon reaching or exceeding these limits, the input value automatically wraps to the other end of the range. Wrap-around of the input value may be prevented by setting software position limits as defined in the software position limit object (607Dh).
<b>Object Code</b>	Array
<b>Data Type</b>	Integer32

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x2
<b>Lower Limit</b>	0x2
<b>Upper Limit</b>	0x2
<b>Sub-Index</b>	001
<b>Description</b>	Min Position Range Limit
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x80000000
<b>Unit</b>	user-defined position
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x80000000

<b>Sub-Index</b>	002
<b>Description</b>	Max Position Range Limit
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x7FFFFFFF
<b>Unit</b>	user-defined position
<b>Lower Limit</b>	0x7FFFFFFF
<b>Upper Limit</b>	0x7FFFFFFF

## 607Ch – Home Offset

### Object Description

<b>Index</b>	607C
<b>Description</b>	<p>This object indicates the difference between the zero position for the application and the machine home position. After the machine home position is found and homing is completed, the zero position is offset from the home position by adding the home offset value to the home position. All subsequent absolute moves are executed relative to this new zero position.</p> <p>If this object is not implemented, home offset is considered to be 0. Negative values indicate the opposite direction.</p>
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	user-defined position
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 607Dh – Software Position Limit

### Object Description

<b>Index</b>	607D
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<b>Description</b>	This object indicates the maximum and minimum software position limits. These parameters define the absolute position limits for the position demand value and the position actual value. Every new target position is checked against these limits. The limit positions are always relative to the machine home position. Before being compared to the target position, they are corrected internally by the home offset, as follows: Corrected min position limit = (min position limit - home offset) Corrected max position limit = (max position limit - home offset)
<b>Object Code</b>	Array
<b>Data Type</b>	Integer32

#### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x2
<b>Lower Limit</b>	0x2
<b>Upper Limit</b>	0x2

  

<b>Sub-Index</b>	001
<b>Description</b>	Minimum Software Position Limit
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x80000001
<b>Unit</b>	user-defined position
<b>Lower Limit</b>	0x80000001
<b>Upper Limit</b>	0x7FFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Maximum Software Position Limit
<b>Data Type</b>	Integer32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x7FFFFFFF
<b>Unit</b>	user-defined position
<b>Lower Limit</b>	0x80000001
<b>Upper Limit</b>	0x7FFFFFFF

## 607Eh – Polarity

### Object Description

<b>Index</b>	607E
<b>Description</b>	Position demand value and position actual value are multiplied by 1 or -1, depending on the value of the polarity flag.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned8

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x1

## 6081h – Profile Velocity

### Object Description

<b>Index</b>	6081
<b>Description</b>	This object indicates the commanded velocity normally attained at the end of the acceleration ramp during a profiled motion. It is valid for both directions of motion. This object is used in profile position mode and interpolated position mode.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read/Write
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<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x2710
<b>Unit</b>	user-defined velocity
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

## 6083h – Profile Acceleration

### Object Description

<b>Index</b>	6083
<b>Description</b>	This object indicates the commanded acceleration. This object is used in the profile position mode, profile velocity mode, and interpolated position mode.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x3E8
<b>Unit</b>	user-defined acceleration
<b>Lower Limit</b>	0x1
<b>Upper Limit</b>	0x1FBD0

## 6084h – Profile Deceleration

### Object Description

<b>Index</b>	6084
<b>Description</b>	This object indicates the deceleration. This object is used in the profile position mode, profile velocity mode, and interpolated position mode.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x3E8
<b>Unit</b>	user-defined acceleration
<b>Lower Limit</b>	0x1

<b>Upper Limit</b>	0x1FBD0
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## 6085h – Quick Stop Deceleration

### Object Description

<b>Index</b>	6085
<b>Description</b>	This object indicates the deceleration used to stop the motor when the quick stop function is activated and the quick stop option code is set to 2 or 6. The quick stop deceleration is also used if the fault reaction option code is 2 and the halt option code is 2.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x2710
<b>Unit</b>	user-defined acceleration
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x1FBD0

## 6086h – Motion Profile Type

### Object Description

<b>Index</b>	6086
<b>Description</b>	This object indicates the type of motion profile used to perform a profiled motion. The following value definitions are valid: 0 = linear ramp (trapezoidal profile)
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer16

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0000
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0x0000

## 6089h – Position Notation Index

**Object Description**

<b>Index</b>	6089
<b>Description</b>	The position notation index is used to scale the objects for which it mandatory. Note: the value of this object is fixed to factor = 1.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer8

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x0

**608Ah – Position Dimension Index****Object Description**

<b>Index</b>	608A
<b>Description</b>	This object indicates position units. Note: the value of this object is fixed to steps.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned8

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xAC
<b>Lower Limit</b>	0xAC
<b>Upper Limit</b>	0xAC

**608Bh – Velocity Notation Index****Object Description**

<b>Index</b>	608B
<b>Description</b>	The velocity notation index is used to scale the objects for which it mandatory. Note: the value of this object is fixed at 0.01.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer8

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xFE
<b>Lower Limit</b>	0xFE
<b>Upper Limit</b>	0xFE

**608Ch – Velocity Dimension Index****Object Description**

<b>Index</b>	608C
<b>Description</b>	This object indicates velocity units. Note: the value of this object is fixed at rpm.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned8

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xA4
<b>Lower Limit</b>	0xA4
<b>Upper Limit</b>	0xA4

**608Dh – Acceleration Notation Index****Object Description**

<b>Index</b>	608D
<b>Description</b>	The acceleration notation index is used to scale the objects for which it mandatory. Note: the value of this object is fixed tat 0.01.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer8

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xFE
<b>Lower Limit</b>	0xFE
<b>Upper Limit</b>	0xFE

## 608Eh – Acceleration Dimension Index

### Object Description

<b>Index</b>	608E
<b>Description</b>	This object indicates acceleration units. Note: the value of this object is fixed at rpm/second
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned8

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xA4
<b>Lower Limit</b>	0xA4
<b>Upper Limit</b>	0xA4

## 608Fh – Position Encoder Resolution

### Object Description

<b>Index</b>	608F
<b>Description</b>	This object indicates the configured encoder increments and number of motor revolutions. It is calculated by the following formula: position encoder resolution = (encoder increments/motor revolutions)
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x2
<b>Lower Limit</b>	0x2
<b>Upper Limit</b>	0x2

<b>Sub-Index</b>	001
<b>Description</b>	Encoder Increments
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x1
<b>Unit</b>	counts
<b>Lower Limit</b>	0x1
<b>Upper Limit</b>	0xFFFFFFFF



<b>Sub-Index</b>	002
<b>Description</b>	Motor Revolutions
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x1
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0x1
<b>Upper Limit</b>	0xFFFFFFFF

## 6098h – Homing Method

### Object Description

<b>Index</b>	6098
<b>Description</b>	<p>This object indicates the homing method to be used. The following value definitions are valid:</p> <ul style="list-style-type: none"> <li>-4 = homing on hard stop in positive direction with Index</li> <li>-3 = homing on hard stop in negative direction with Index</li> <li>-2 = homing on hard stop in positive direction</li> <li>-1 = homing on hard stop in negative direction</li> <li>0 = no homing method assigned</li> <li>1 = homing method 1 to be used</li> <li>.</li> <li>.</li> <li>36 = homing method 36 to used</li> <li>-x = manufacturer-specific</li> </ul>
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer8

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x01
<b>Lower Limit</b>	0xFC
<b>Upper Limit</b>	0x23

## 6099h – Homing Speeds

### Object Description

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<b>Index</b>	6099
<b>Description</b>	This object indicates the commanded speeds used during homing procedure.
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned32

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**Entry Description**

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x2
<b>Lower Limit</b>	0x2
<b>Upper Limit</b>	0x2

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<b>Sub-Index</b>	001
<b>Description</b>	Fast Homing Speed
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x3E8
<b>Unit</b>	user-defined velocity
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

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<b>Sub-Index</b>	002
<b>Description</b>	Slow Homing Speed
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x3E8
<b>Unit</b>	user-defined velocity
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x7FFFFFFF

## 609Ah – Homing Acceleration

### Object Description

<b>Index</b>	609A
<b>Description</b>	This object indicates the acceleration and deceleration to be used during homing operation.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x3E8
<b>Unit</b>	user-defined acceleration
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x1FBD0

## 60B8h – Touch Probe Function

### Object Description

<b>Index</b>	60B8
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<b>Description</b>	<p>Indicates the configured function of the touch probe. This object is organized bit-wise. The bits have the following meaning:</p> <p><b>Bit Description</b></p> <p>0: 0 = switch off touch probe 1 1 = enable touch probe 1</p> <p>1: 0 = trigger first event 1 = continuous</p> <p>2: 0 = trigger touch probe 1 input 1 = trigger with zero pulse signal or position encoder</p> <p>3: Reserved</p> <p>4: 0 = switch off sampling at positive edge of touch probe 1 1 = enable sampling at positive edge of touch probe 1</p> <p>5: 0 = switch off sampling at negative edge of touch probe 1 1 = enable sampling at negative edge of touch probe 1</p> <p>6,7: User-defined (e.g. for testing)</p> <p>8: 0 = switch off touch probe 2 1 = enable touch probe 2</p> <p>9: 0 = trigger first event 1 = continuous</p> <p>10: 0 = trigger with touch probe 2 input 1 = trigger with zero pulse signal or position encoder</p> <p>11: Reserved</p> <p>12: 0 = switch off sampling at positive edge of touch probe 2 1 = enable sampling at positive edge of touch probe 2</p> <p>13: 0 = switch off sampling on negative edge of touch probe 2 1 = enable sampling at negative edge of touch probe 2</p> <p>14,15: user-defined (e.g., for testing)</p>
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0xFFFF

## 60B9h – Touch Probe Status

### Object Description

<b>Index</b>	60B9
<b>Description</b>	<p>Indicates the status of the touch probe. This object is organized bit-wise. The bits have the following meaning:</p> <p><b>Bit Description</b></p> <p>0: 0 = touch probe 1 is switched off 1 = touch probe 1 is enabled</p> <p>1: 0 = touch probe 1 no positive edge value stored 1 = touch probe 1 negative edge position stored</p> <p>2: 0 = touch probe 1 no negative edge value stored 1 = touch probe 1 positive edge position stored</p> <p>3-5: Reserved</p> <p>6,7: User-defined (e.g. for testing)</p> <p>8: 0 = touch probe 2 is switched off 1 = touch probe 2 is enabled</p> <p>9: 0 = touch probe 2 no positive edge value stored 1 = touch probe 2 negative edge position stored</p> <p>10: 0 = touch probe 2 no negative edge value stored 1 = touch probe 2 positive edge position stored</p> <p>11-13: Reserved</p> <p>14,15: User-defined (e.g. for testing)</p>
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned16

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00
<b>Lower Limit</b>	0x0000
<b>Upper Limit</b>	0xFFFF

## 60BAh – Touch Probe 1 Position Positive Value

### Object Description

<b>Index</b>	60BA
<b>Description</b>	The position value of touch probe 1 at the positive edge.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00
<b>Unit</b>	user-defined position
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 60BBh – Touch Probe 1 Position Negative Value

### Object Description

<b>Index</b>	60BB
<b>Description</b>	The position value of touch probe 1 at the negative edge.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00
<b>Unit</b>	user-defined position
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 60BCh – Touch Probe 2 Position Positive Value

### Object Description

<b>Index</b>	60BC
<b>Description</b>	The position value of touch probe 2 at the positive edge.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00
<b>Unit</b>	user-defined position
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 60BDh – Touch Probe 2 Position Negative Value

### Object Description

<b>Index</b>	60BD
<b>Description</b>	The position value of touch probe 2 at the negative edge.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00
<b>Unit</b>	user-defined position
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 60C2h – Interpolation Time Period

### Object Description

<b>Index</b>	60C2
<b>Description</b>	This object indicates the configured interpolation cycle time. This object has the following sub-indexes: sub-index 1: value of the time sub-index 2: dimension index of the time value in sub-index 1
<b>Object Code</b>	Record
<b>Data Type</b>	P402_IP_PERIOD_T

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x2
<b>Unit</b>	time units
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFF

<b>Sub-Index</b>	001
<b>Description</b>	time units
<b>Data Type</b>	Unsigned8
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x4
<b>Unit</b>	milliseconds
<b>Lower Limit</b>	0x1
<b>Upper Limit</b>	0x10



<b>Sub-Index</b>	002
<b>Description</b>	time index
<b>Data Type</b>	Integer8
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xFD
<b>Unit</b>	Not Applicable
<b>Lower Limit</b>	0xFD
<b>Upper Limit</b>	0xFD

## 60C5h – Max Acceleration

### Object Description

<b>Index</b>	60C5
<b>Description</b>	This object indicates the maximum acceleration. It is used to limit the acceleration to an acceptable value in order to prevent the motor and the moved mechanics from being damaged.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	user-defined acceleration
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x1FBD0

## 60C6h – Max Deceleration

### Object Description

<b>Index</b>	60C6
<b>Description</b>	This object indicates the maximum deceleration. It is used to limit the deceleration to an acceptable value in order to prevent the motor and the moved mechanics from being damaged.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Unit</b>	user-defined acceleration
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0x1FBD0

## 60F4h – Following Error Actual Value

### Object Description

<b>Index</b>	60F4
<b>Description</b>	This object indicates the actual value of the following error.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Unit</b>	user-defined position
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 60FAh – Control Effort

### Object Description

<b>Index</b>	60FA
<b>Description</b>	This object indicates the control effort as the output of the position control loop. In the position control function, notation of the control effort is mode-dependent and therefore not specified.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x00000000
<b>Unit</b>	user-defined velocity
<b>Lower Limit</b>	0x80000000

<b>Upper Limit</b>	0x7FFFFFFF
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## 60FDh – Digital Inputs

### Object Description

<b>Index</b>	60FD
<b>Description</b>	<p>This object provides digital inputs.</p> <p>This object is organized bit-wise. The bits have the following meaning:</p> <ul style="list-style-type: none"> <li>bit 0: negative limit switch</li> <li>bit 1: positive limit switch</li> <li>bit 2: home switch</li> <li>bit 3: reserved</li> <li>bit 16-31: manufacturer-specific</li> </ul> <p>The bit values have the following meaning:</p> <ul style="list-style-type: none"> <li>0 = switch is off</li> <li>1 = switch is on</li> </ul>
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 60FEh – Digital Outputs

### Object Description

<b>Index</b>	60FE
<b>Description</b>	<p>This object commands simple digital outputs.</p> <p>This object is organized bit-wise. The bits have the following meaning:</p> <ul style="list-style-type: none"> <li>bit 16-31: manufacturer-specific</li> </ul> <p>This object includes the following sub-indexes:</p> <ul style="list-style-type: none"> <li>sub-index 1: the physical output value</li> <li>sub-index 2: mask for the physical outputs</li> </ul>
<b>Object Code</b>	Array
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Sub-Index</b>	000
<b>Description</b>	Number of entries
<b>Access</b>	Read Only
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x2
<b>Lower Limit</b>	0x1
<b>Upper Limit</b>	0x2
<b>Sub-Index</b>	001
<b>Description</b>	Physical Outputs The bit values for sub-index 1 have the following meaning: 0 = output is off, brake is not set 1 = output is on, brake is set
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

<b>Sub-Index</b>	002
<b>Description</b>	Output Mask The bit values for sub-index 2 have the following meaning: 0 = disable output (output will not change) 1 = enable output (output will change)
<b>Data Type</b>	Unsigned32
<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x0
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 60FFh – Target Velocity

### Object Description

<b>Index</b>	60FF
<b>Description</b>	This object indicates the configured target velocity and is used as input for the trajectory generator.
<b>Object Code</b>	Variable
<b>Data Type</b>	Integer32

### Entry Description

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	Yes
<b>Default Value</b>	0x0
<b>Unit</b>	user-defined velocity
<b>Lower Limit</b>	0x80000000
<b>Upper Limit</b>	0x7FFFFFFF

## 6402h – Motor Type

### Object Description

<b>Index</b>	6402
<b>Description</b>	This object indicates the type of motor attached to and driven by the drive device. The following value definition is valid:  0008h = stepper motor 0009h = micro-step stepper motor
<b>Object Code</b>	Variable

<b>Data Type</b>	Unsigned16
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**Entry Description**

<b>Access</b>	Read/Write
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x8
<b>Lower Limit</b>	0x8
<b>Upper Limit</b>	0x9

**6502h – Supported Drive Modes****Object Description**

<b>Index</b>	6502
<b>Description</b>	<p>This object provides information about the supported drive modes.</p> <p>This object is organized bit-wise. The bits have the following meaning:</p> <ul style="list-style-type: none"> <li>bit 0: profile position mode</li> <li>bit 1: velocity mode</li> <li>bit 2: profile velocity mode</li> <li>bit 3: profile torque mode</li> <li>bit 4: reserved</li> <li>bit 5: homing mode</li> <li>bit 6: interpolated position mode</li> <li>bit 7: cyclic synchronous position mode</li> <li>bit 8: cyclic synchronous velocity mode</li> <li>bit 9: cyclic synchronous torque mode</li> <li>bit 10-15: reserved</li> <li>bit 16-31: manufacturer-specific</li> </ul> <p>The bit values have the following meaning:</p> <ul style="list-style-type: none"> <li>0 = mode is not supported</li> <li>1 = mode is supported</li> </ul>
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

**Entry Description**

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0xAF
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

## 67FFh – Single Device Type

### Object Description

<b>Index</b>	67FF
<b>Description</b>	This object defines the type of the specific drive within a multi-device module. This object has the same structure as object 1000h (device type). This object is organized bit-wise.
<b>Object Code</b>	Variable
<b>Data Type</b>	Unsigned32

### Entry Description

<b>Access</b>	Read Only
<b>PDO Mapping</b>	No
<b>Default Value</b>	0x00000192
<b>Lower Limit</b>	0x0
<b>Upper Limit</b>	0xFFFFFFFF

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